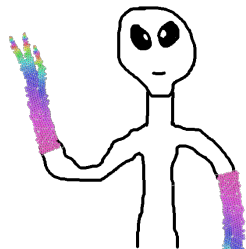




# A multiagent approach for virtual tissue morphogenesis

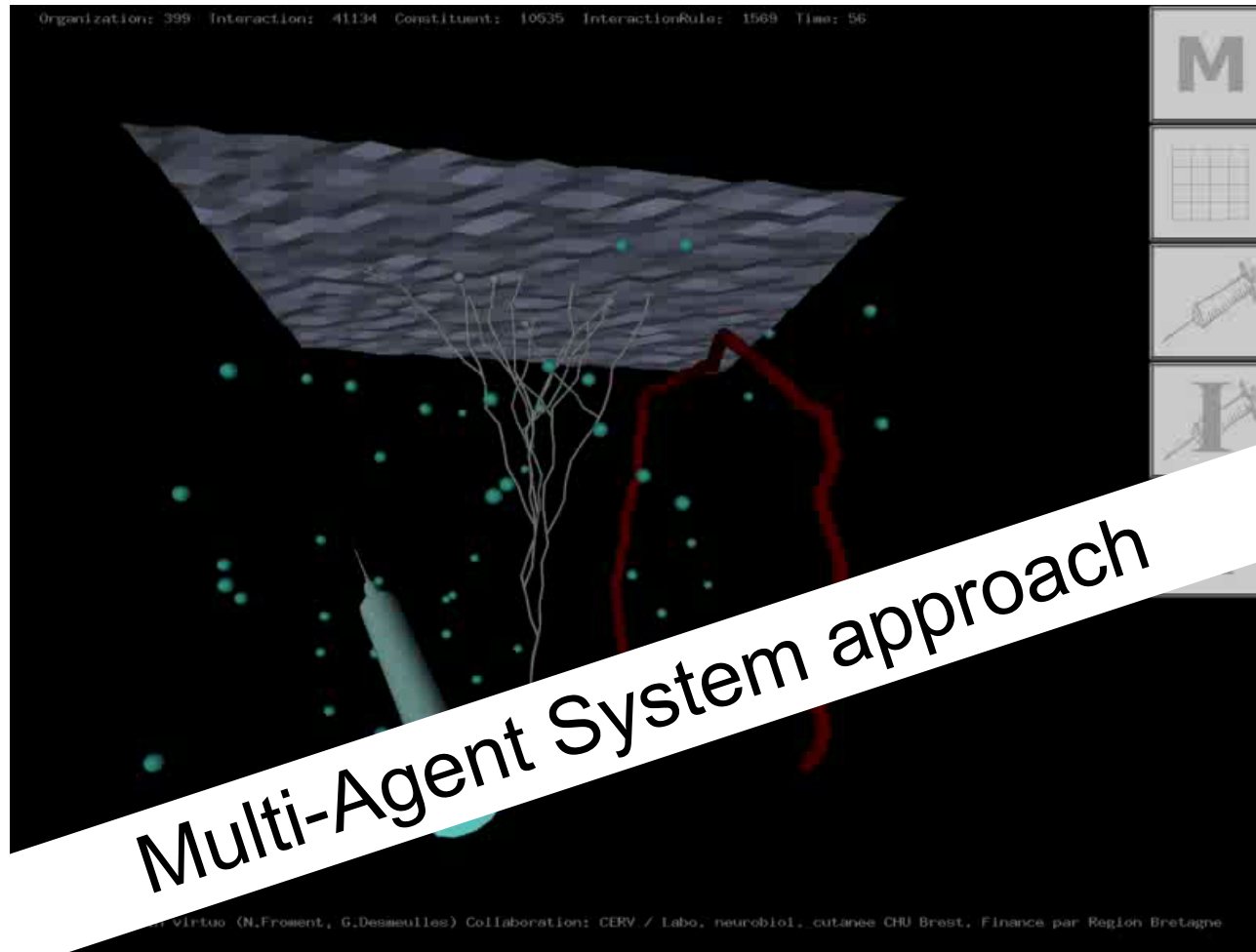
Vincent Rodin,  
Anne Jeannin-Girardon, Abdoulaye Sarr,  
J r my Rivier , Alexandra Fronville, Pascal Ballet



Lab-STICC, UMR 6285, CNRS,  
Computer Science Dept,  
University of Brest, France



## Virtual Reality → Virtual Biology

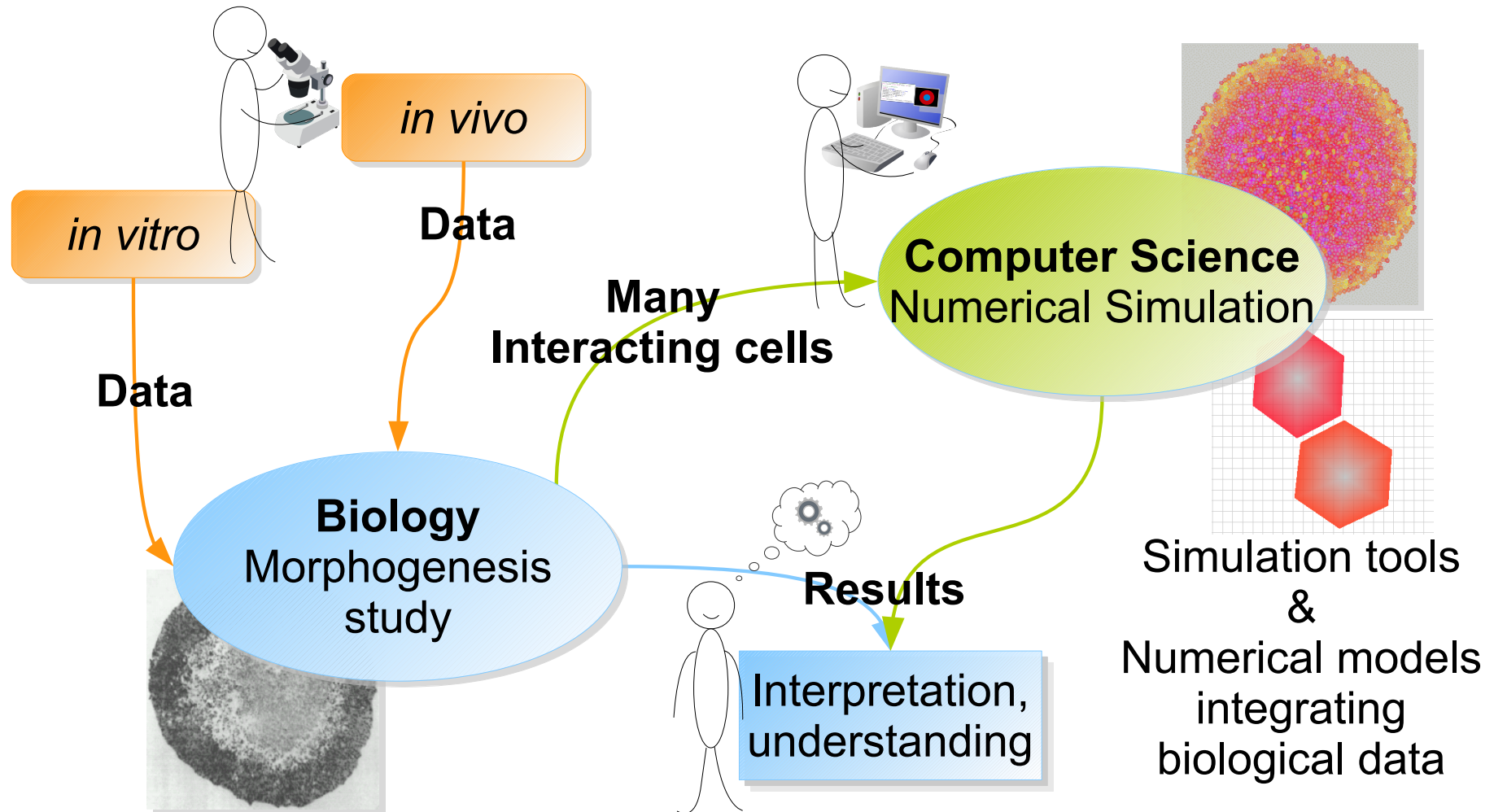


Interaction between virtual cells and/or molecules

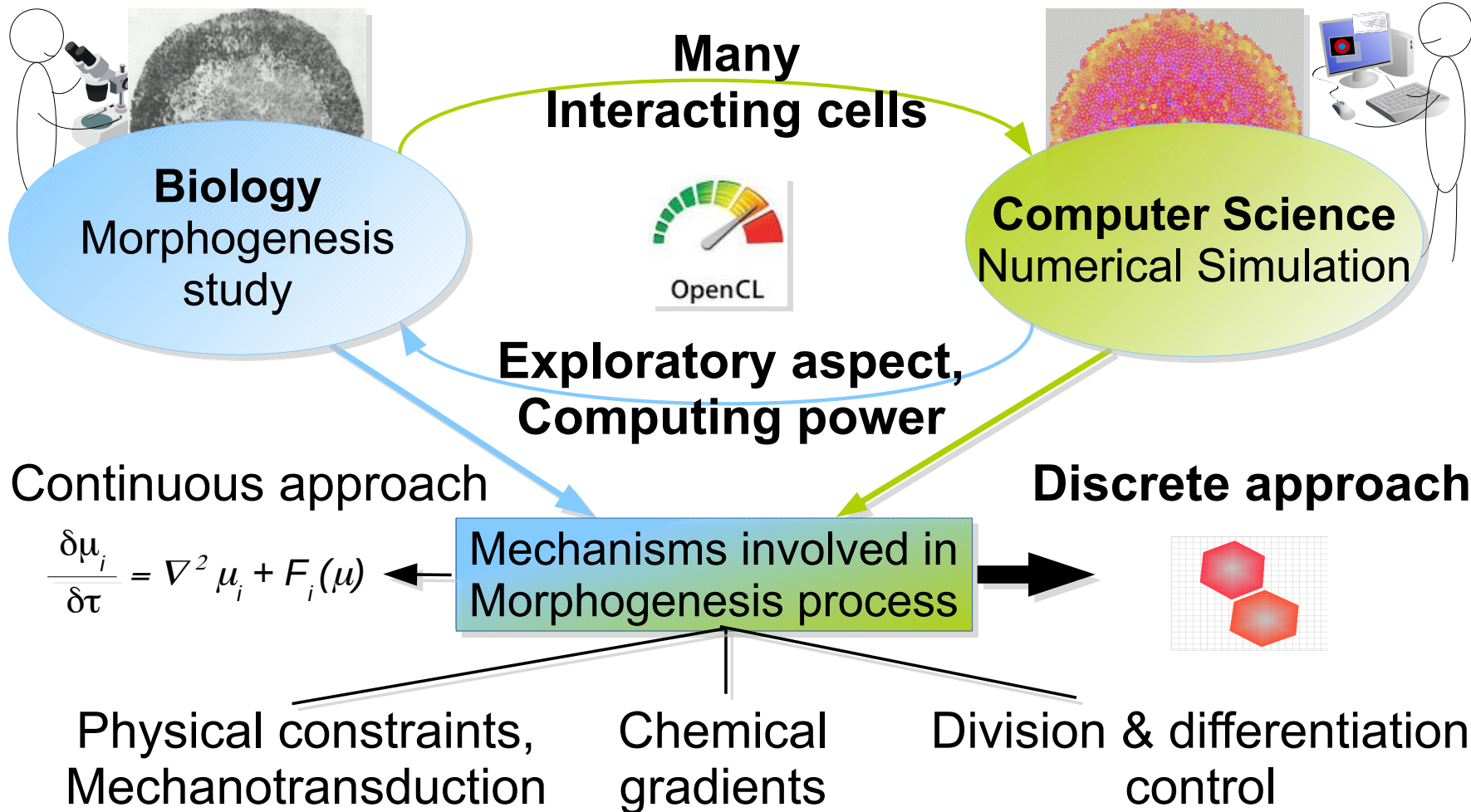
2



# Context (1/3)



# Context (2/3)



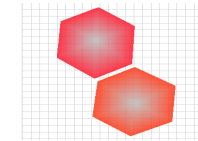


Continuous approach

$$\frac{\delta \mu_i}{\delta \tau} = \nabla^2 \mu_i + F_i(\mu)$$

Mechanisms involved in Morphogenesis process

Discrete approach



Physical constraints,  
Mechanotransduction

Chemical  
gradients

Division & differentiation  
control

Ph.D. Anne Jeannin-Girardon

« Research & Technical challenge »  
work

Ph.D. Abdoulaye Sarr

« Exploratory research »  
work

A. Jeannin-Girardon et Al, IEEE/ACM Transactions on Computational Biology and Bioinformatics (TCBB), 2015

A. Sarr et Al, 3<sup>rd</sup> international conference on Theory and Practice of Natural Computing (TPNC), 2014



- Introduction
- Virtual cell model
  - ➔ Structure, cycle, abilities, interactions & constraints
- Virtual chemistry model
- Parallel implementation
  - ➔ OpenCL, model coupled with a MAS,  $10^6$  cells
- Starfish growth... a simplified model
- Towards morphogenesis modeling ?
- Morphogenesis modeling : our approach based on viability
- Morphogenesis modeling : our model, a case study
- Future works

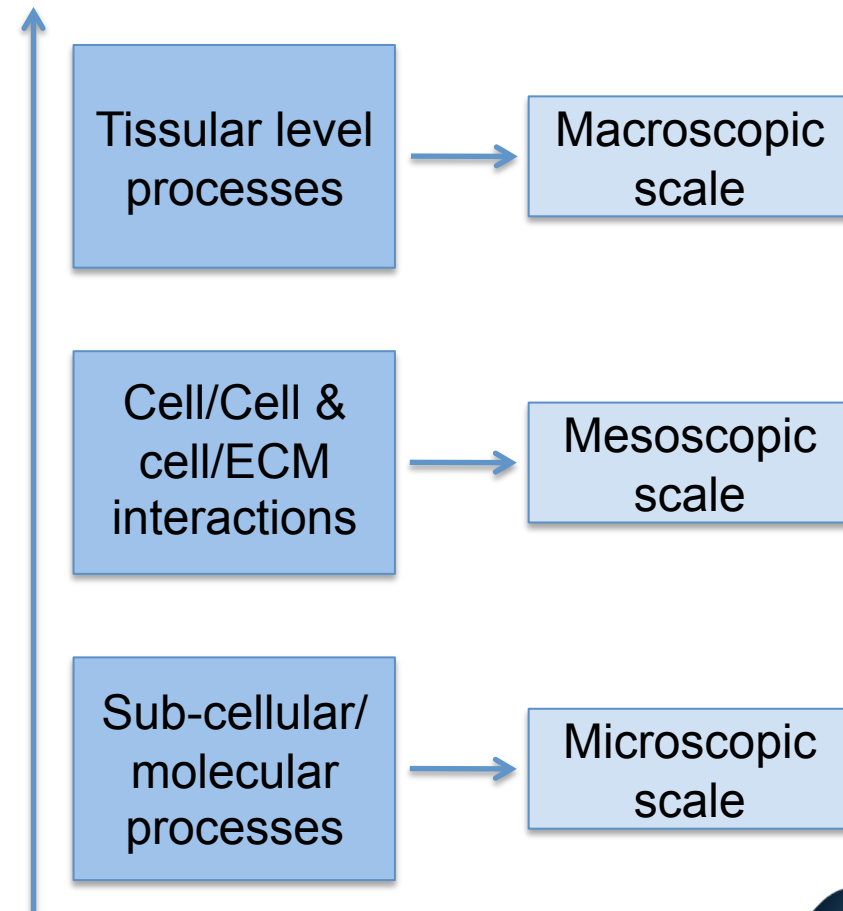
# Introduction (1/4)



## Tissue morphogenesis:



- Is a multi-scale phenomenon
- Can be addressed through continuous/discrete models
- Involves many of interacting entities (cells, molecules, etc.)



# Introduction (2/4)



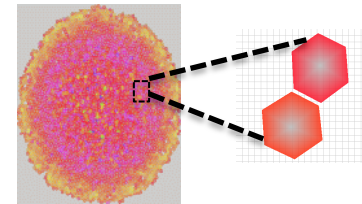
## Tissue morphogenesis: continuous VS discrete approaches

### Continuous approaches

$$\frac{\delta\mu_i}{\delta t} = \nabla^2 \mu_i + F_i(\mu)$$

- Consider population instead of individuals
- Adapted for large scale simulation
- Take into account the whole system

### Discrete approaches



- Local interactions definition  
global emerging behaviors
- Require a large amount of computation time
- Can focus on a small part of the system



# Introduction (3/4)

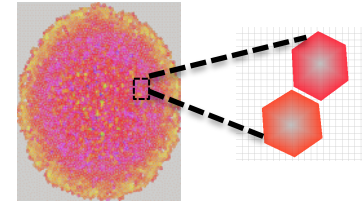


## Tissue morphogenesis: our approach is hybrid

Continuous approaches

$$\frac{\delta\mu_i}{\delta t} = \nabla^2 \mu_i + F_i(\mu)$$

Discrete approaches



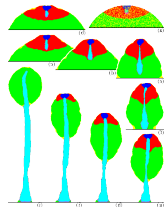
**But, we choose to favor discrete approaches:**

- Discrete modeling of entities allows variability in cell population... and allows cell differentiation
- Individual Based Models (IBM) are often suited for a parallel implementation
- Continuous approach can be used when needed (chemical gradient, etc.)

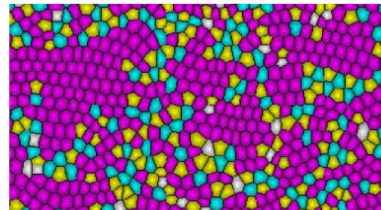


## Discrete cellular models

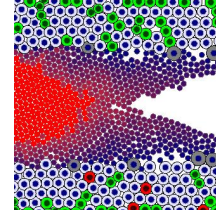
- Some models focus on the internal dynamics of cells
  - ➔ too complex to simulate tissue
- Some models focus on cell behaviors
  - ➔ mitosis, differentiation, etc.



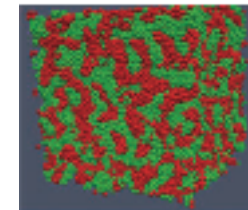
Marée et al, 2001



Li et al, 2012



Macklin et al, 2012



Kang et al, 2014

- Some models are parallelized using various frameworks
  - ➔ OpenMP, MPI, Posix thread, CUDA, openCL, etc.
  - ➔ Laptops, standard PC, Super Computer, Grid, etc.

# Virtual cell model (1/6)

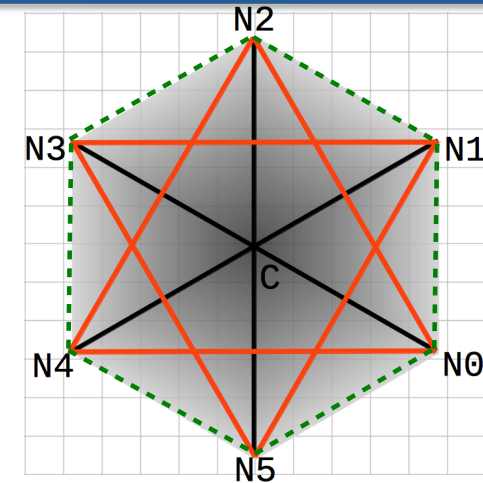


- Virtual cell structure: mass/spring system

- ➔ n+1 nodes

- ➔ membrane, cytoskeleton, cortex

## Cell deformation

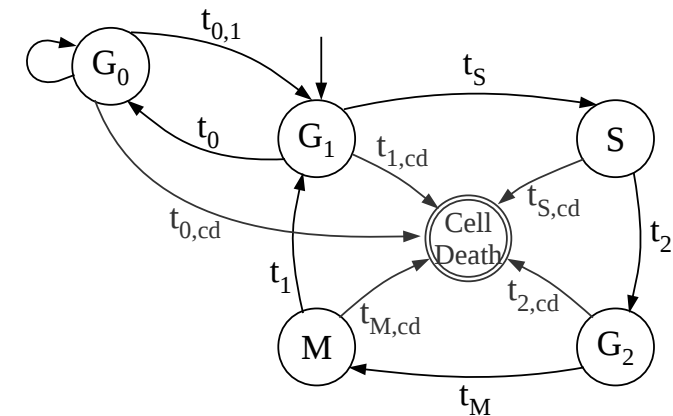


- Virtual cell cycle: very (too) simple one

- ➔ finite-state machine

- ➔ no checkpoint

## Cell control



- Virtual cell mechanotransduction

## Cell physical constraint evaluation



11

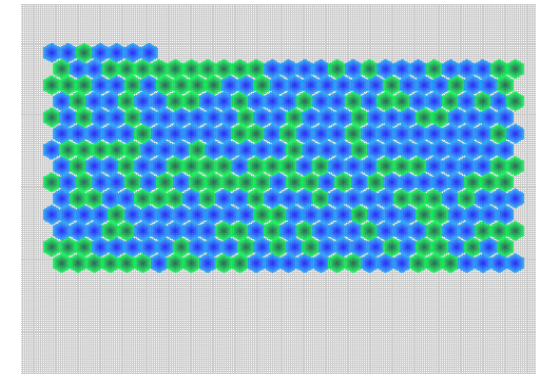
# Virtual cell model (2/6)



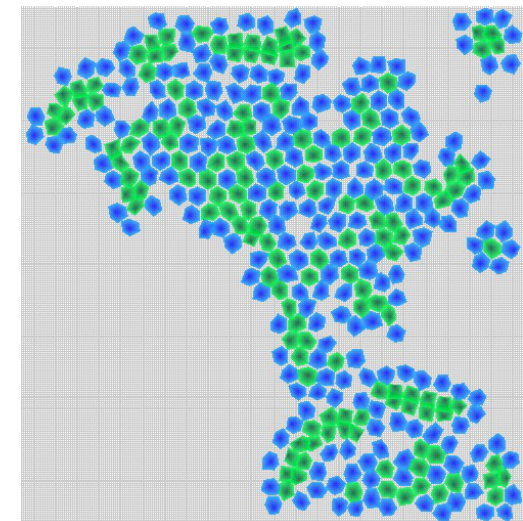
## Virtual cells agents behaviors and abilities

- deformation
- motility
- migration along a molecular gradient
- molecules consumption/production
- differentiation
- mitosis
- apoptosis/necrosis
- cell interactions
- mechanotransduction

Interacting cells



Example: cell sorting

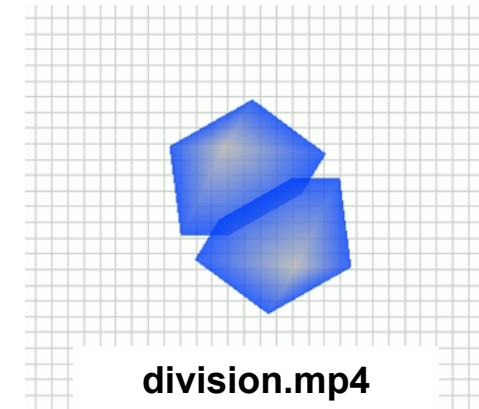
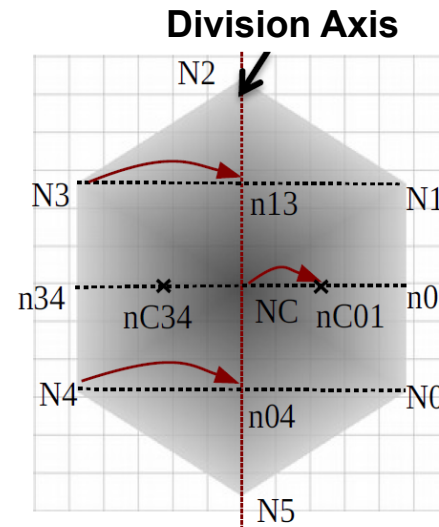




## Mitose and cell interactions

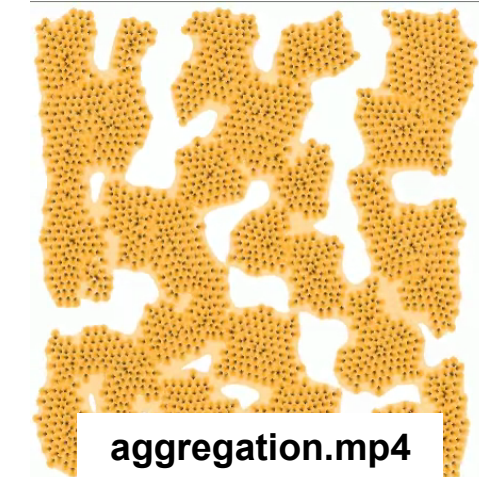
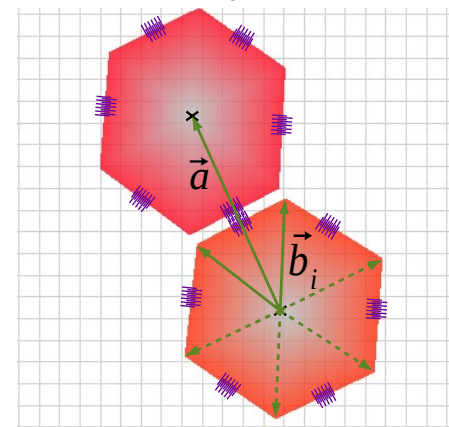
➤ Mitose

➔ orientated mitosis given an axis



➤ Cell adhesion/repulsion

➔ differential interaction: simplified mechanism (selected nodes bind with the center of the neighbouring cell)



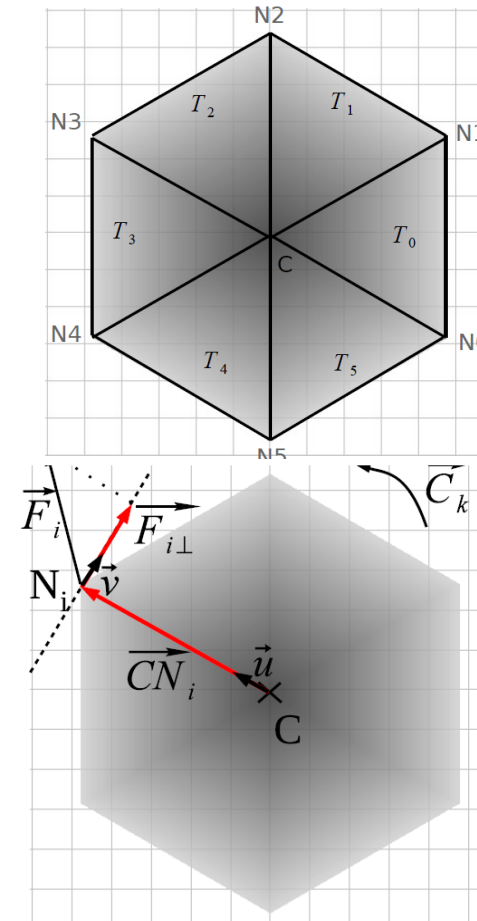
# Virtual cell model (4/6)



## Mechanical constraints evaluation

### → Mechanotransduction ←

- Surface compression/stretching
  - sum of the area triangles composing the cell
  
- Shearing constraints
  - computation of the couple cells ungerdo

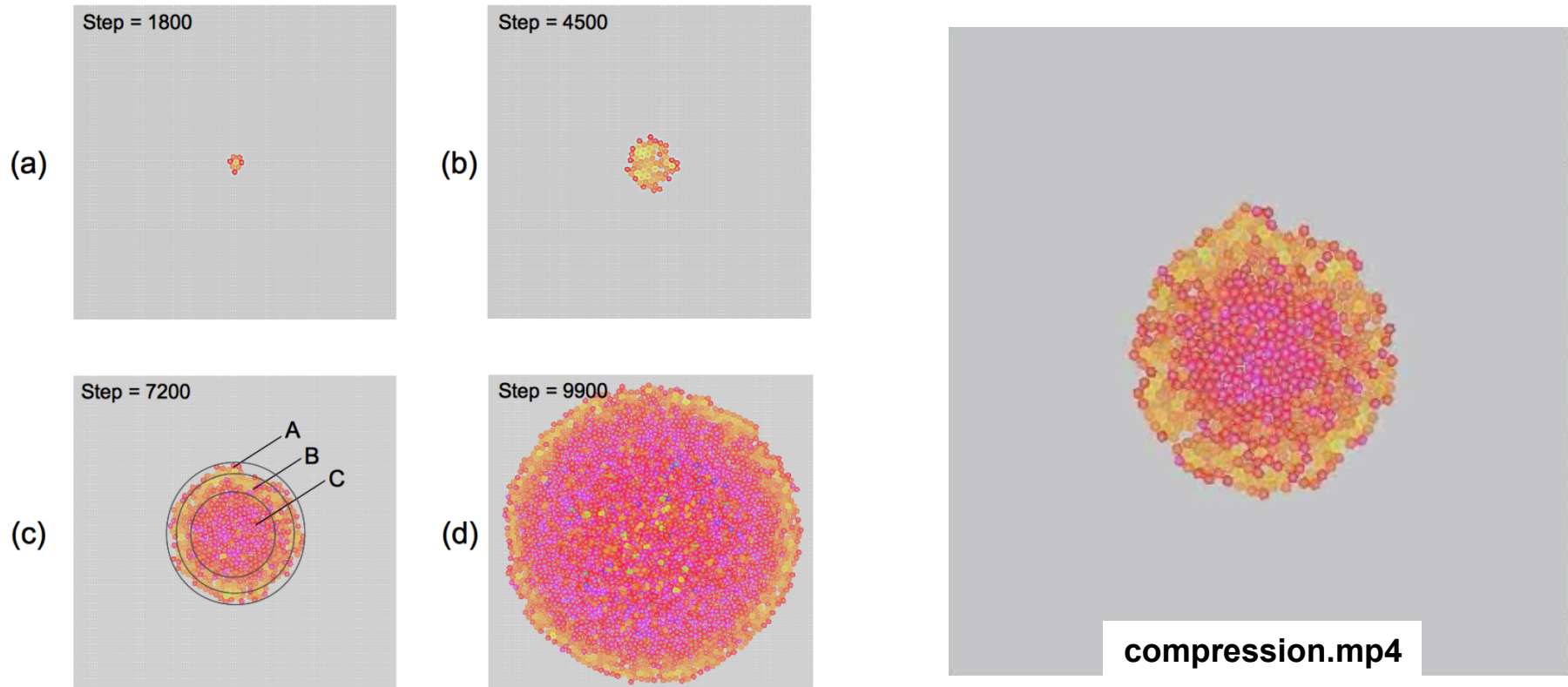


# Virtual cell model (5/6)



**Hypothesis:** The **compression/stretching** constraints cells undergo can induce a differentiation

We represent a cell differentiation by a change in the cell's color

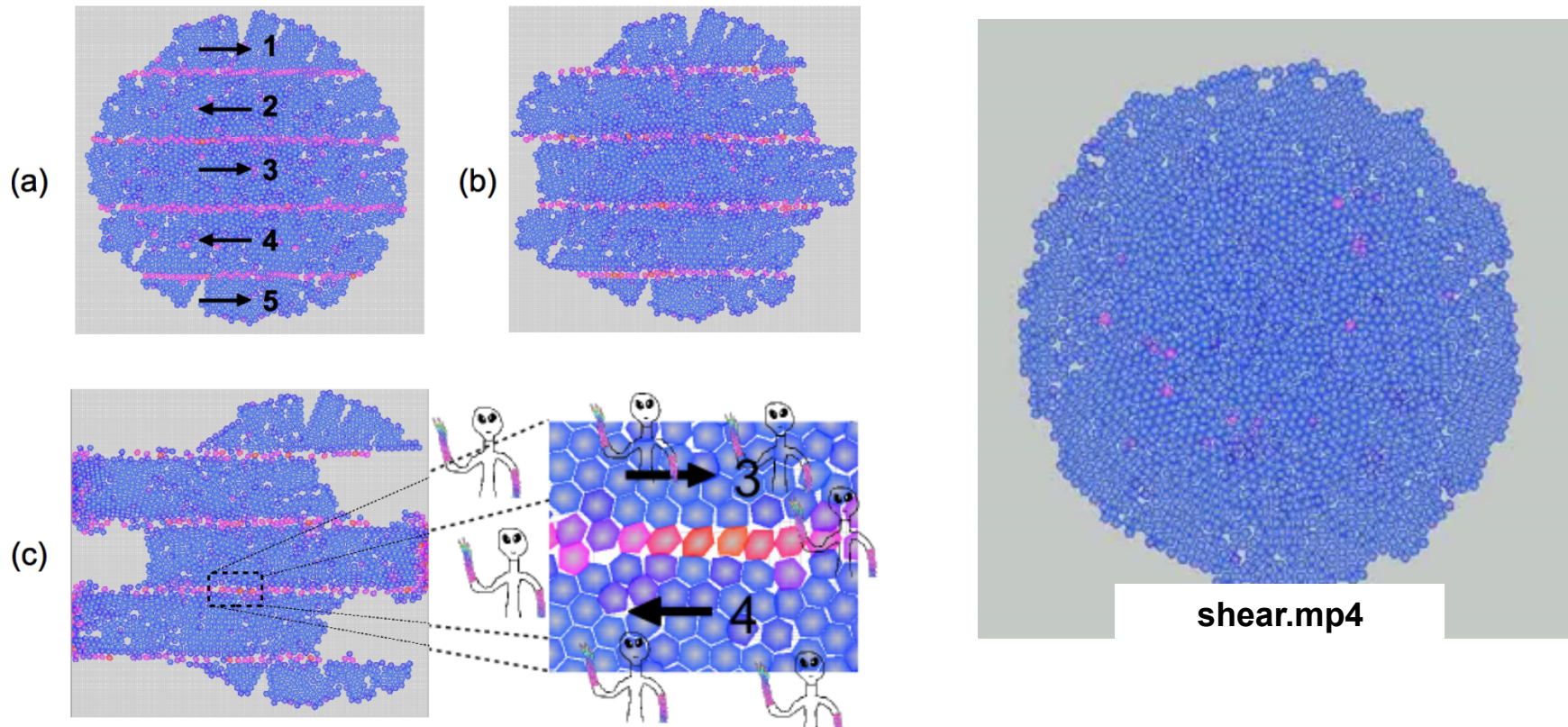


# Virtual cell model (6/6)



**Hypothesis:** The **shearing** constraints cells undergo can induce a differentiation

We represent a cell differentiation by a change in the cell's color



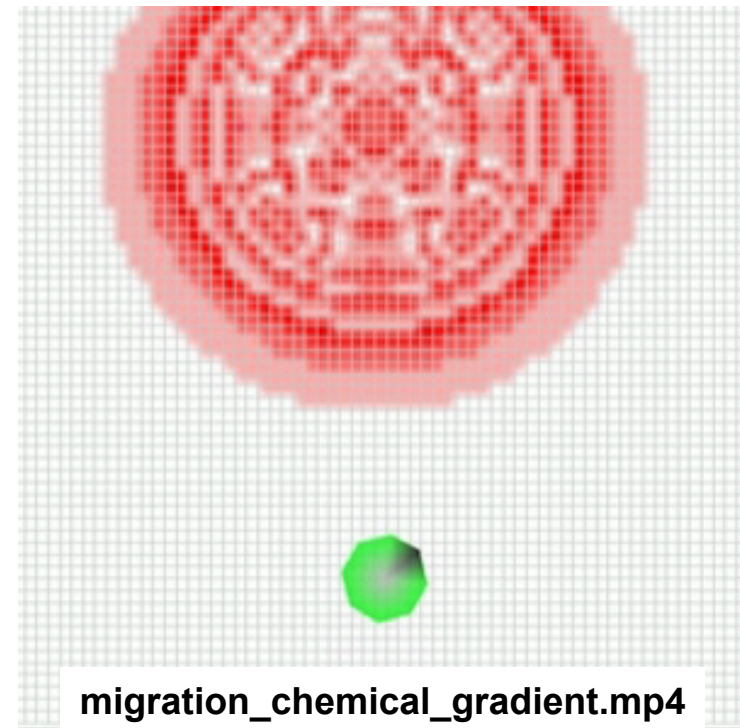




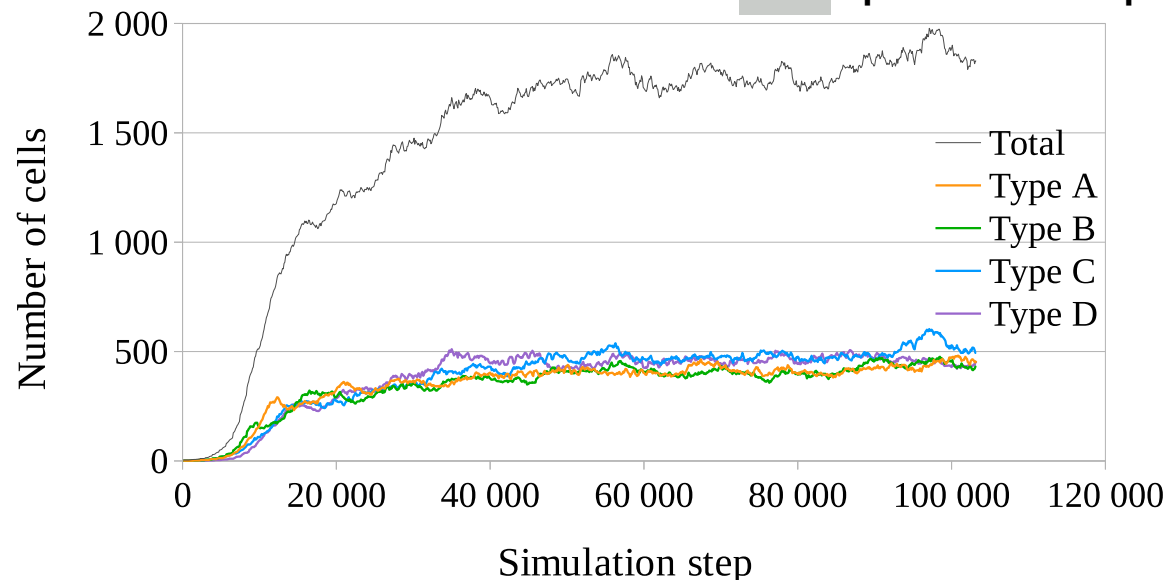
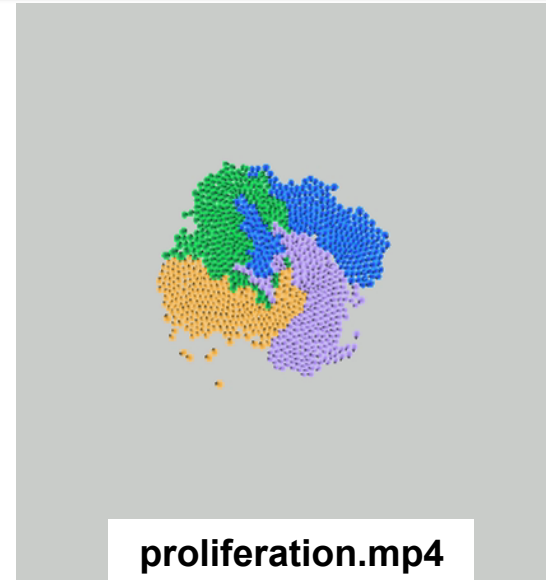
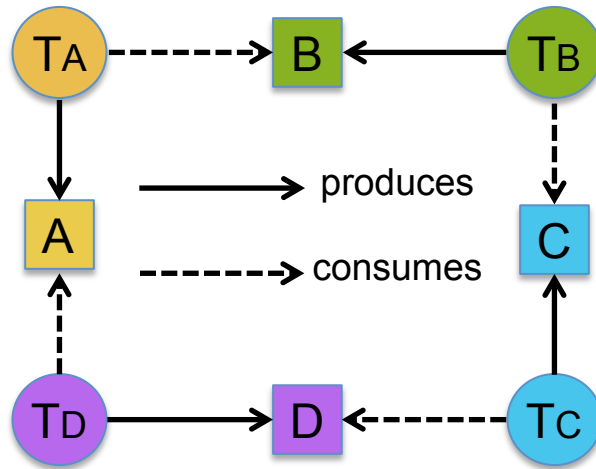
## Discrete molecular level modeled with diffusion/reaction equations

$$\frac{\delta_i(x,t)}{\delta t} = D_i \Delta_i(x,t) - R_i(x,t)$$

- Set of molecules. Ex: {A, B,C}
- Set of reactions. Ex: {2A + B → C}
- Set of 2D discrete layers.  
One grid layer per molecule type
- Equations solved in 2 steps:
  - 1) diffusion
  - 2) reaction



# Virtual chemistry model (2/2)



# Parallel implementation (1/3)



- Parallel hardware and device are everywhere
- Parallel programming gets easier
- Numerous parallel frameworks are available



- Our model seems well adapted to parallel implementation
- We choose to use the **OpenCL framework** to implement it  
➔ we can use CPUs, GPUs, FPGAs, etc.



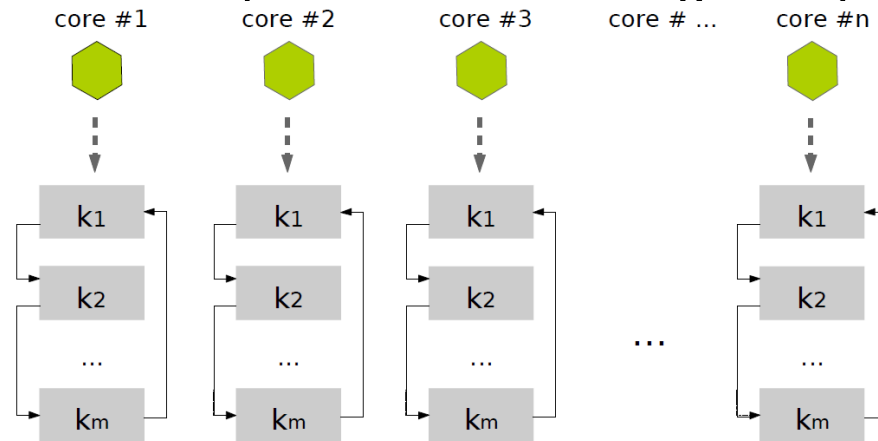
OpenCL

cBio 2015, [vincent.rodin@univ-brest.fr](mailto:vincent.rodin@univ-brest.fr)

# Parallel implementation (2/3)



- Fine grained implementation: a cell = an OpenCL core  
 ➔ model coupled with a Multi-Agent System



Kernel k1: computes forces  
 Kernel k2: integrates forces  
 (Euler method)

- Data stored into structures of arrays: nodes, etc.  
 ➔ adapted data structure for GPU: a cell = an id
- Cells are located in a discrete 2D environment  
 ➔ repulsion: one cell (center node) per grid element ➔ **No synchronization required**
- Virtual chemistry: a chemistry grid element = an OpenCL core  
 ➔ each core, two synchronized tasks: 1) diffusion and 2) reactions

# Parallel implementation (3/3)



Intel Core i7 860  
2.8 GHz, quad-core



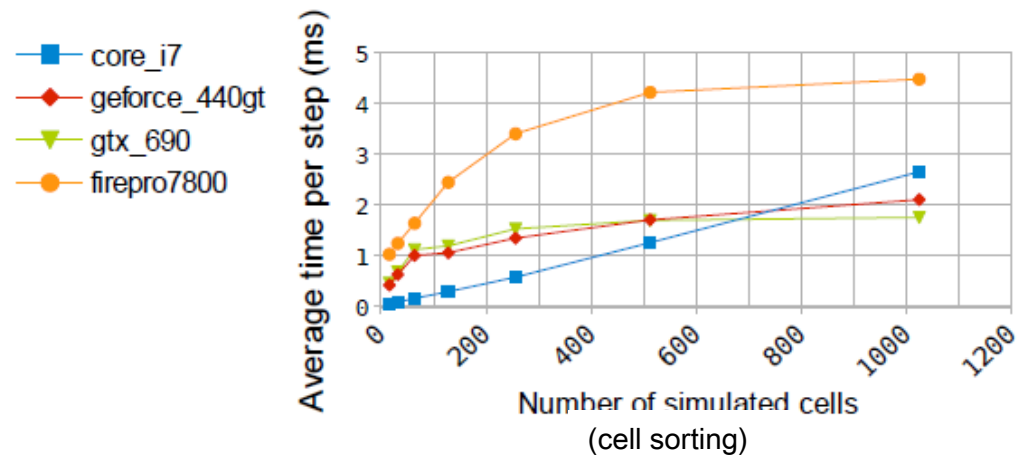
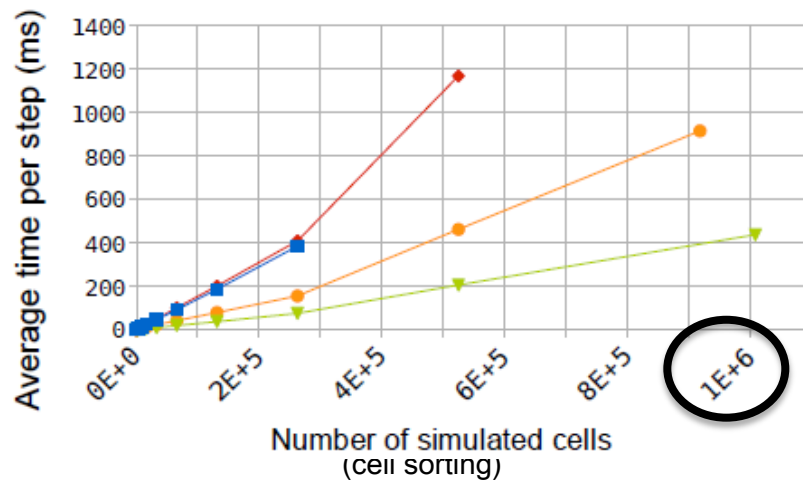
NVidia GeForce GT 440  
1600 MHz, 96 processing  
elements



ATI Firepro 7800  
700 MHz, 1440  
processing elements



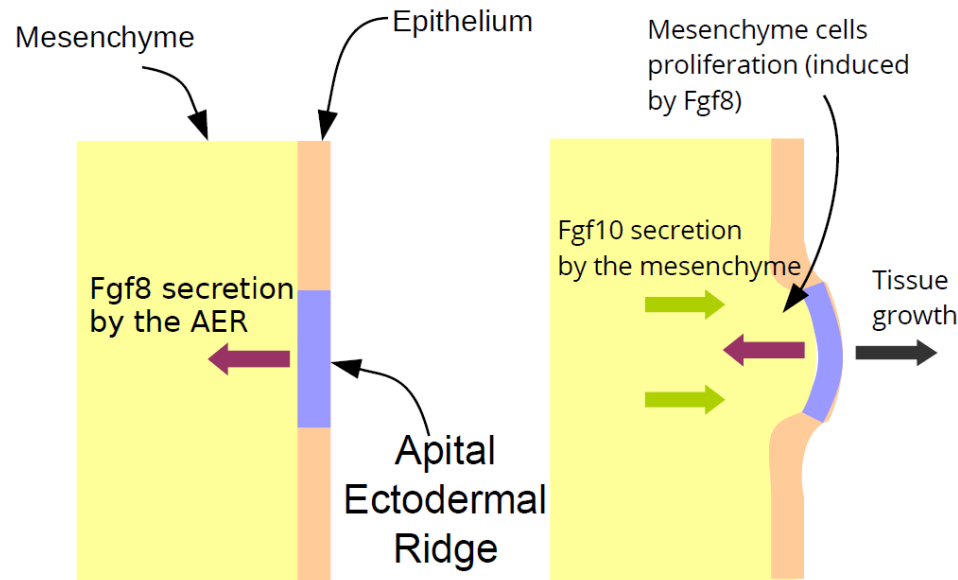
NVidia GeForce GTX  
690  
900 - 1000 MHz, 1536  
processing elements



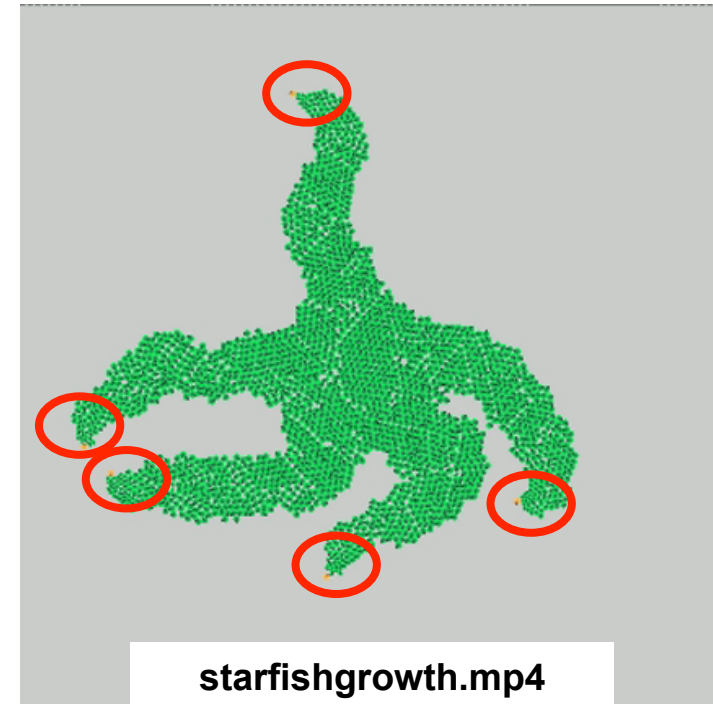
# Starfish growth (1/2)



## a simplified model



- AER Cells secrete Fgf8 molecules
- Fgf8 molecules induce mesenchyme cells proliferation
- Mesenchyme cells response to Fgf8 by secreting Fgf10 molecules
- Fgf10 molecules maintain Fgf8 secretion

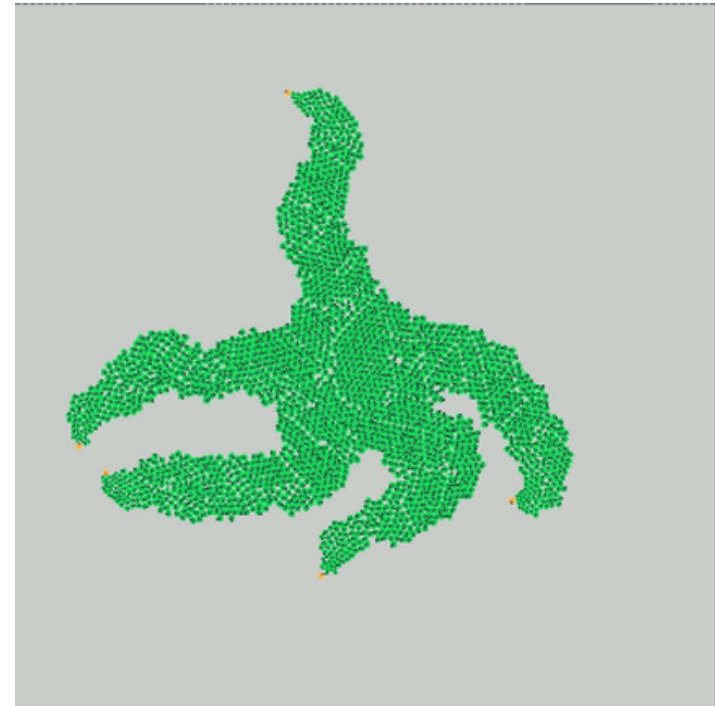


**Problem:** we put the right cells at the right places....

# Starfish growth (2/2)

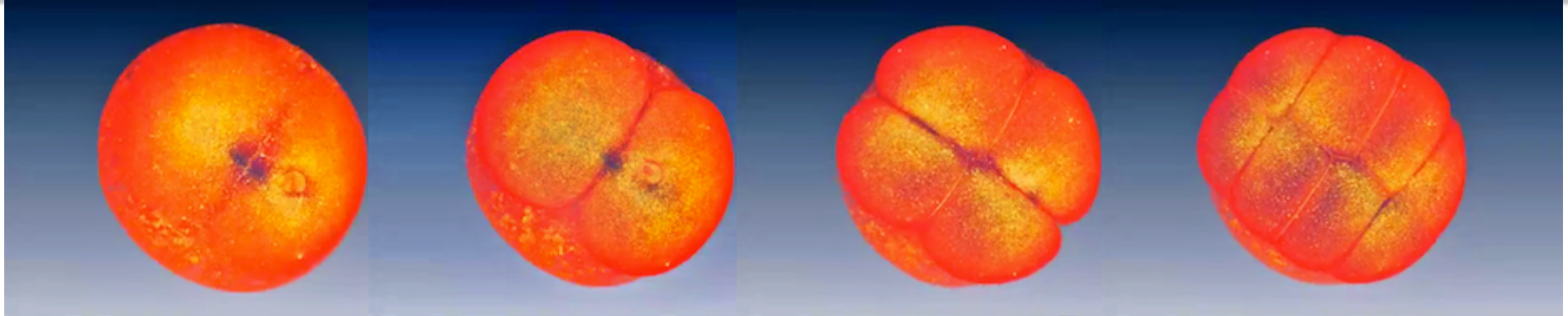


What is the « program » ?



# ... Towards morphogenesis modeling..?(1/2)

occidentale



Early zebrafish embryo, from [N. Olivier et al, 2010]

During early embryogenesis, we can see (probable) :

- Geometric segmentation
- Deterministic process

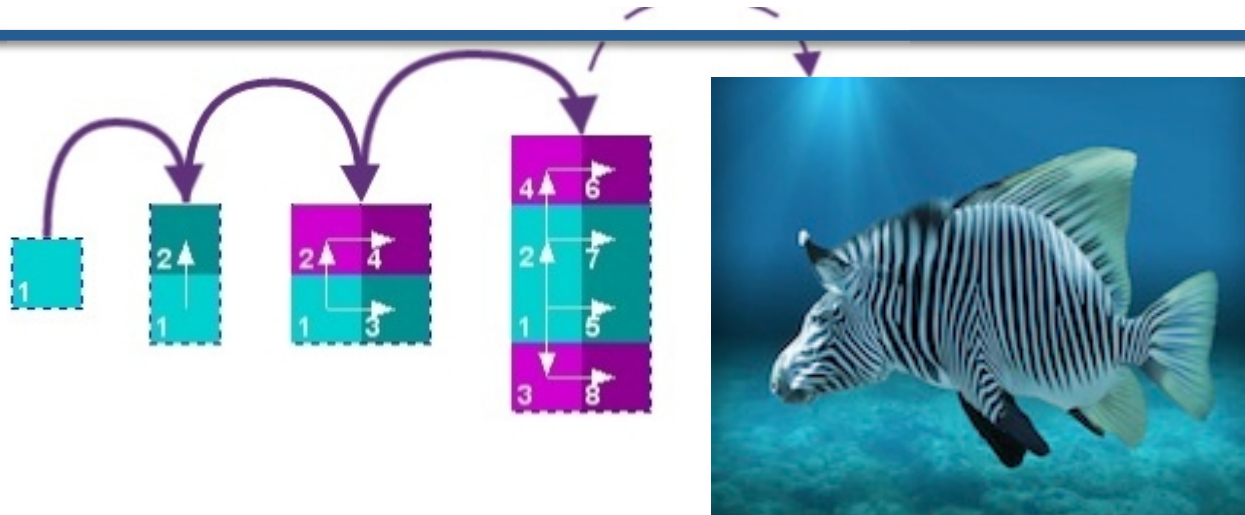
What is the program within cells that controls their placement and their differentiation at the early embryogenesis ?



...

# Towards morphogenesis modeling..?(1/2)

occidentale



Idea:

- Find a mathematical model of a well-guided morphogenesis
- Generate, from a single cell, all early tissues and the associate programs

Problem:

- Huge number of possibilities !

Our response:

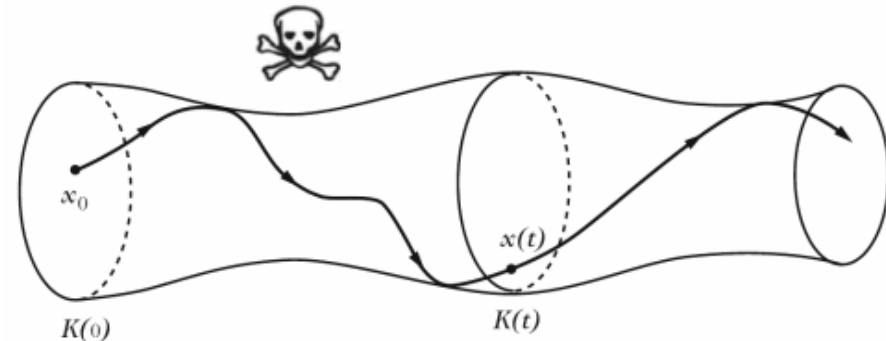
- Tissue morphogenesis is a viability problem !



## Our approach (1/2)

Our response:

- Tissue morphogenesis is a viability problem !



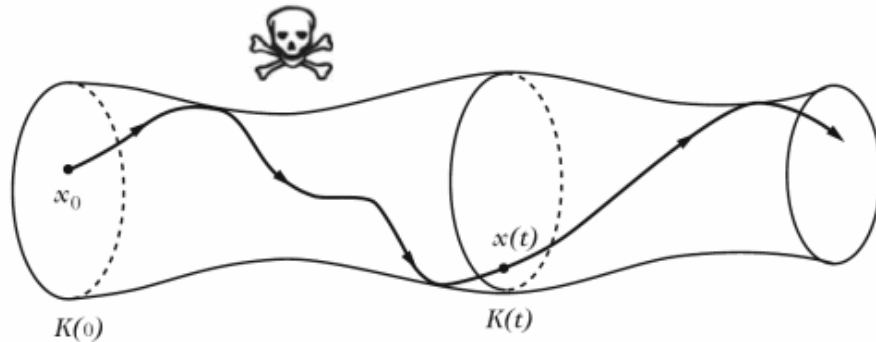
Graph of viable evolution in a *tube*,  
from [J.P. Aubin, 2001]

Viability Theory (J.P. Aubin, 1991)

- Offers concepts and methods to control a dynamic system to remain in a set of constraints.



## Our approach (2/2)



Graph of viable evolution in a *tube*,  
from [J.P. Aubin, 2001]

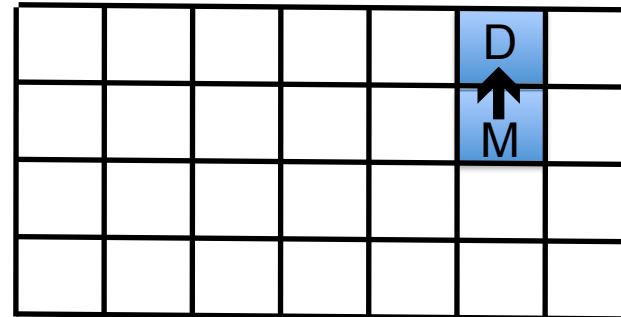
Viability concepts in morphogenesis

- A shape is a **state**
- The directions of division are the **controls**
- The tissues evolve under **constraints**
- A shape can be set as a **target**




## Our model (1/2)

- The Environment  $E$ : a grid



$x$ : **M**other cell  
 $d=1$   
 $x \longrightarrow x + 1$   
 Create **D**aughter

- A cell  $x$  : a square which can be placed in the environment 
- A genetic action  $d$  which can be applied by a cell :

$d \in \{ \uparrow, \downarrow, \rightarrow, \leftarrow, \blacksquare, \emptyset \}$  or simply  $d \in \{ 1, 2, 3, 4, 5, 6 \}$

A genetic action  $d$  allow to describe a cell action :

1. Division :  $x \longrightarrow x + d$ , where  $d \in \{ 1, 2, 3, 4 \}$  (action)
2. Quiescence :  $x \longrightarrow x + 5 = x$  (*no action*)
3. Apoptosis :  $x \longrightarrow x + 6 = 6$  (*programmed cell death*)



## Our model (2/2)

- A genetic process  $G$  : an ordered list of different genetic actions  
Example:  $G = \{ 1, 3, 2, 4, 5, 6 \} \dots$  A cell control

AT EACH STEP, a cell will apply this algorithm using  $G$ :

```
for ( action = 0 ; action < G.length ; action = action + 1 )
```

```
{
  if (G[action] can be applied)
```

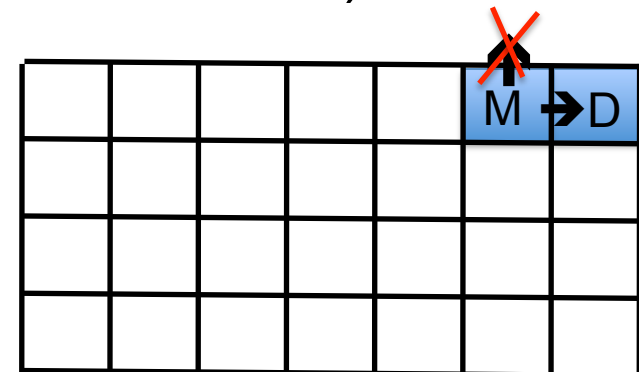
```
{
```

```
  Apply G[action]
```

```
  break; /* out of the loop, AT EACH STEP
```

```
    only one action is applied ! */
```

```
}
```



Currently, when a mitose occurs,  
 $G$  is transmitted to the daughter cell...




## A case study (1/5)

From a single cell  :

- What are the all possible tissues to get after a given number of divisions (phenotypes) ?
- For each attained tissue, what is the minimal underlying genetic process  $G$  that governed cell division and differentiation (genotypes)?

Implementation:

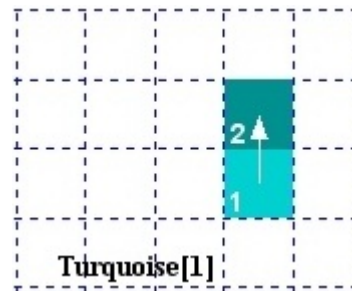
- In 2D, discrete in time and space
- Evolutions of tissues stored using Boost Graph
- Removal of duplicated evolutions :  
same shapes by geometric transformation...  87% less !

# Morphogenesis modeling :



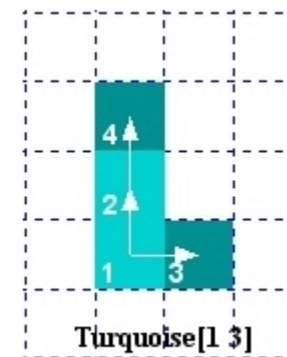
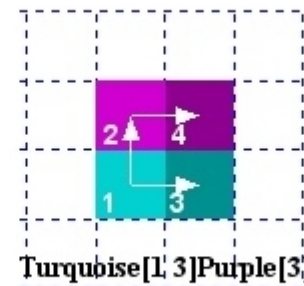
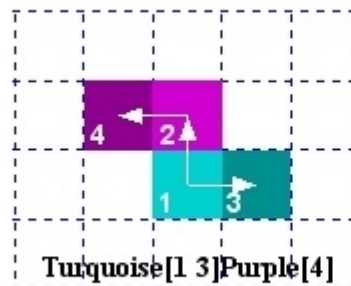
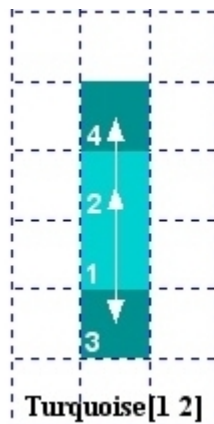
## A case study (2/5)

Attainable tissues after 1 division: 1



2 cells

Attainable tissues after 2 divisions: 4



4 cells



## A case study (3/5)

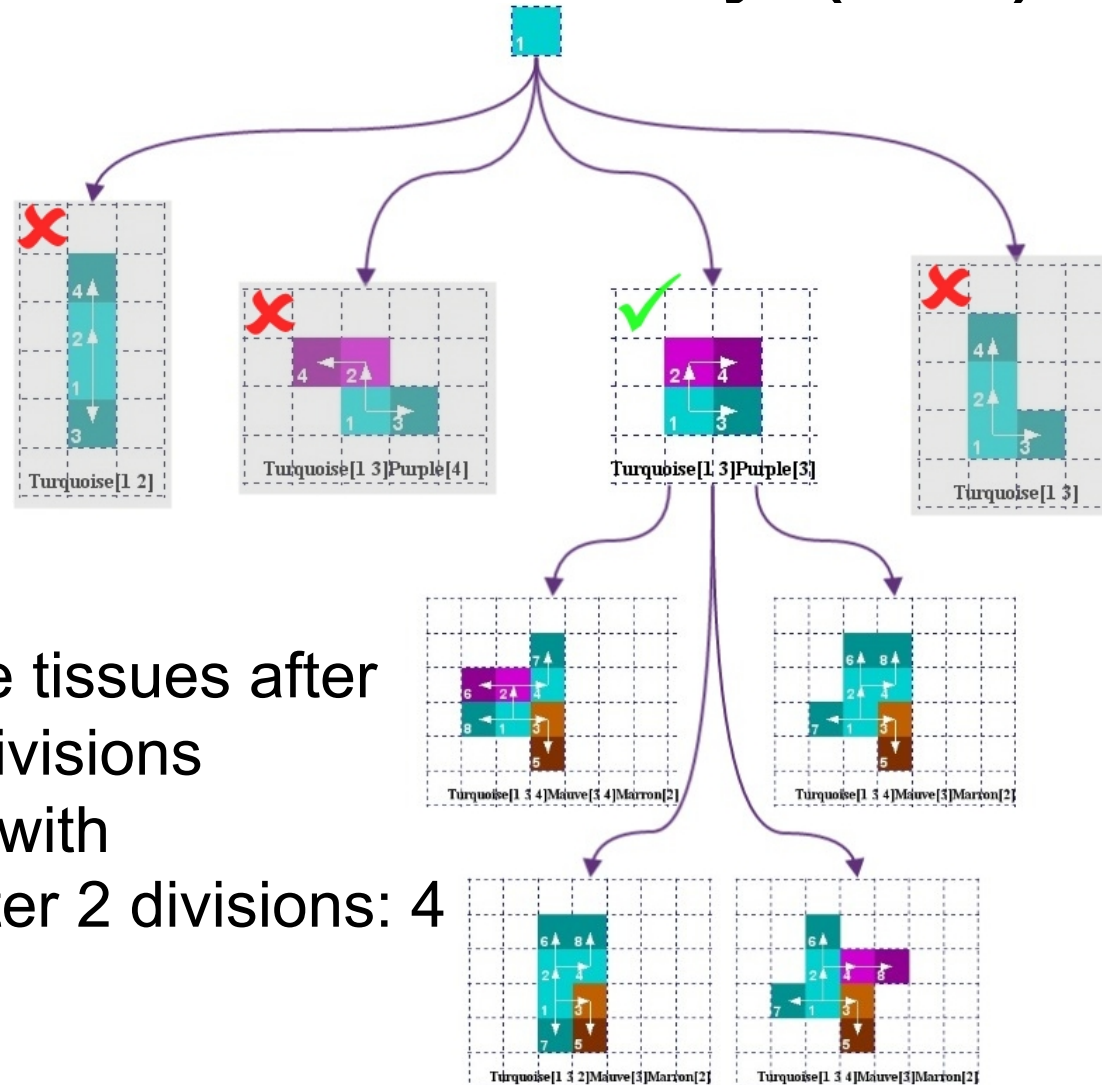
Attainable tissues after 3 divisions: 61







## A case study (3/5)



Attainable tissues after  
 3 divisions  
 with  
 selecting after 2 divisions: 4

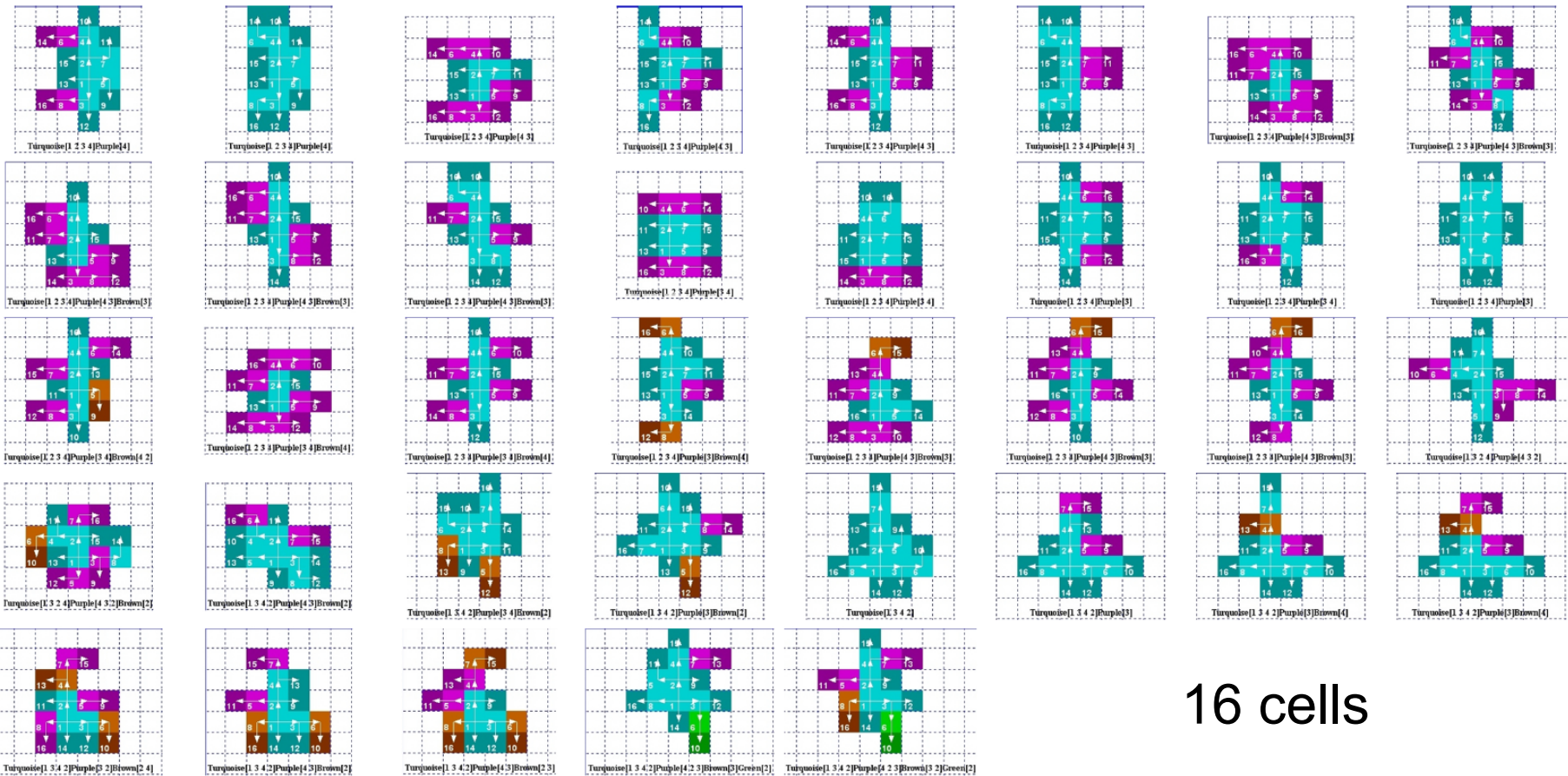
8 cells

# Morphogenesis modeling :



## A case study (4/5)

Attainable tissues after 4 divisions: 1029



16 cells

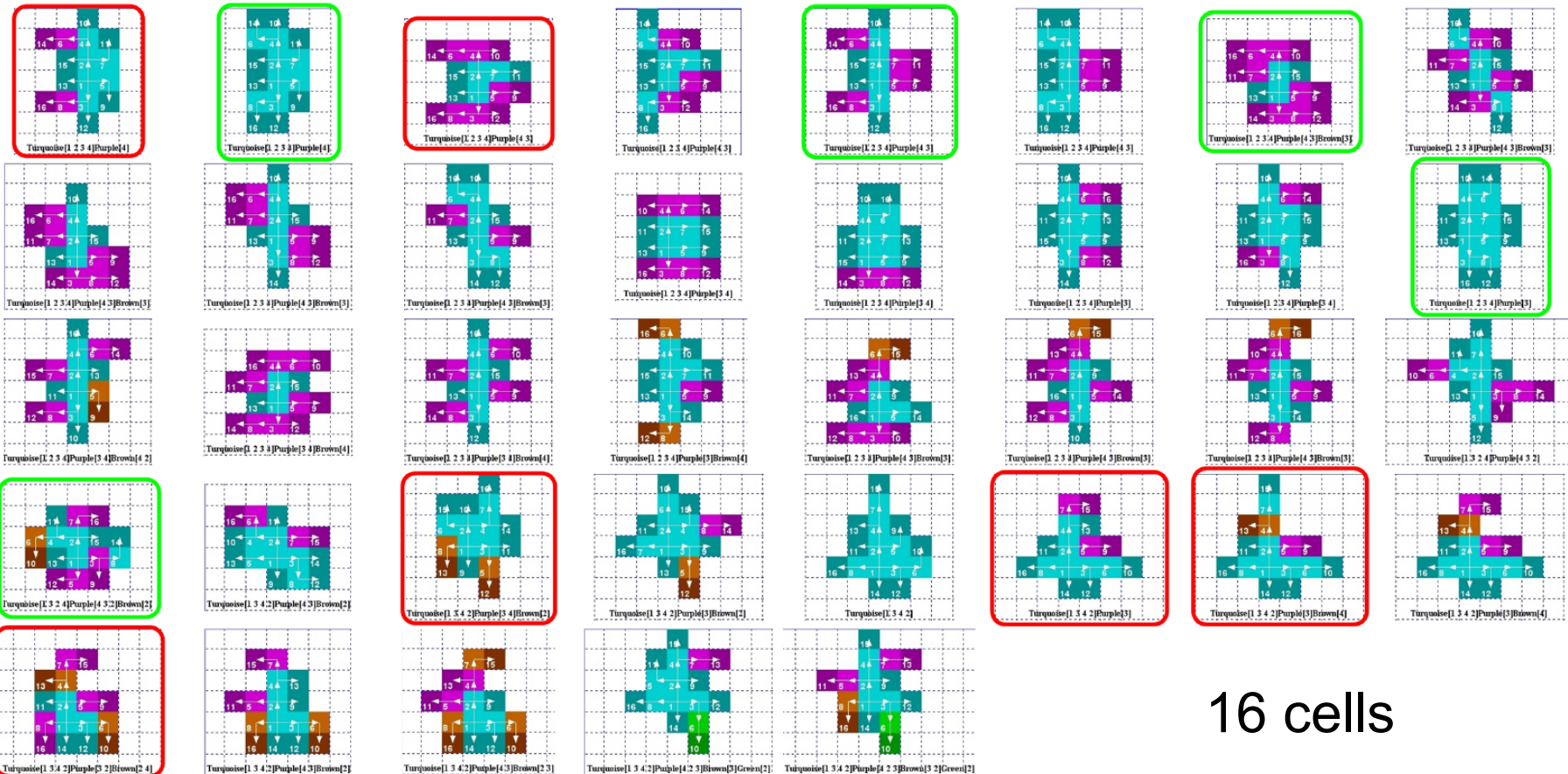


# Morphogenesis modeling :



## A case study (5/5)

Selection with regard to symmetry, robustness and bio-inspiration of tissues



16 cells

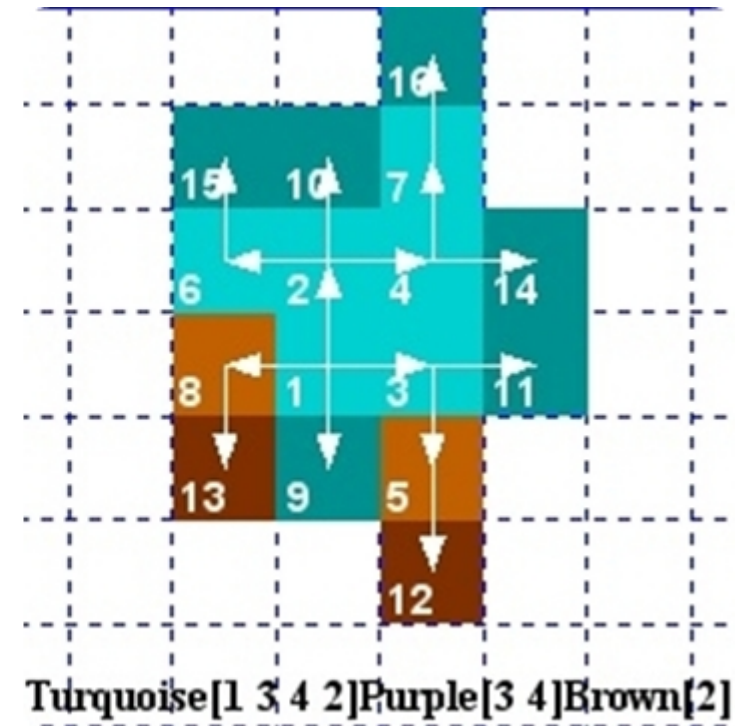


# Morphogenesis modeling :



## A case study (5/5)

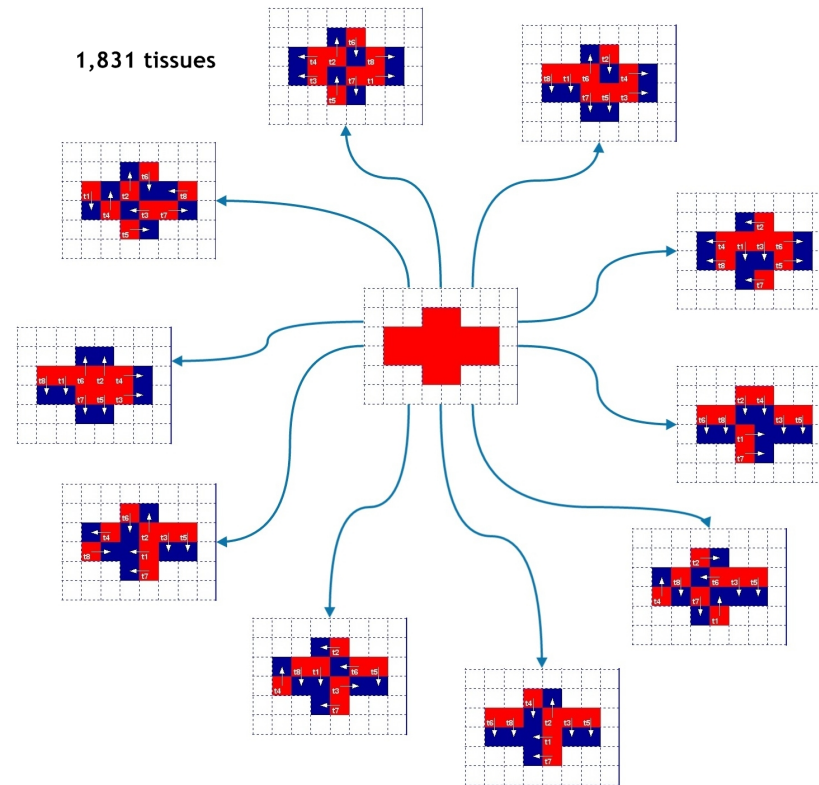
An example that highlights the link between phenotype and genotype



# Future works

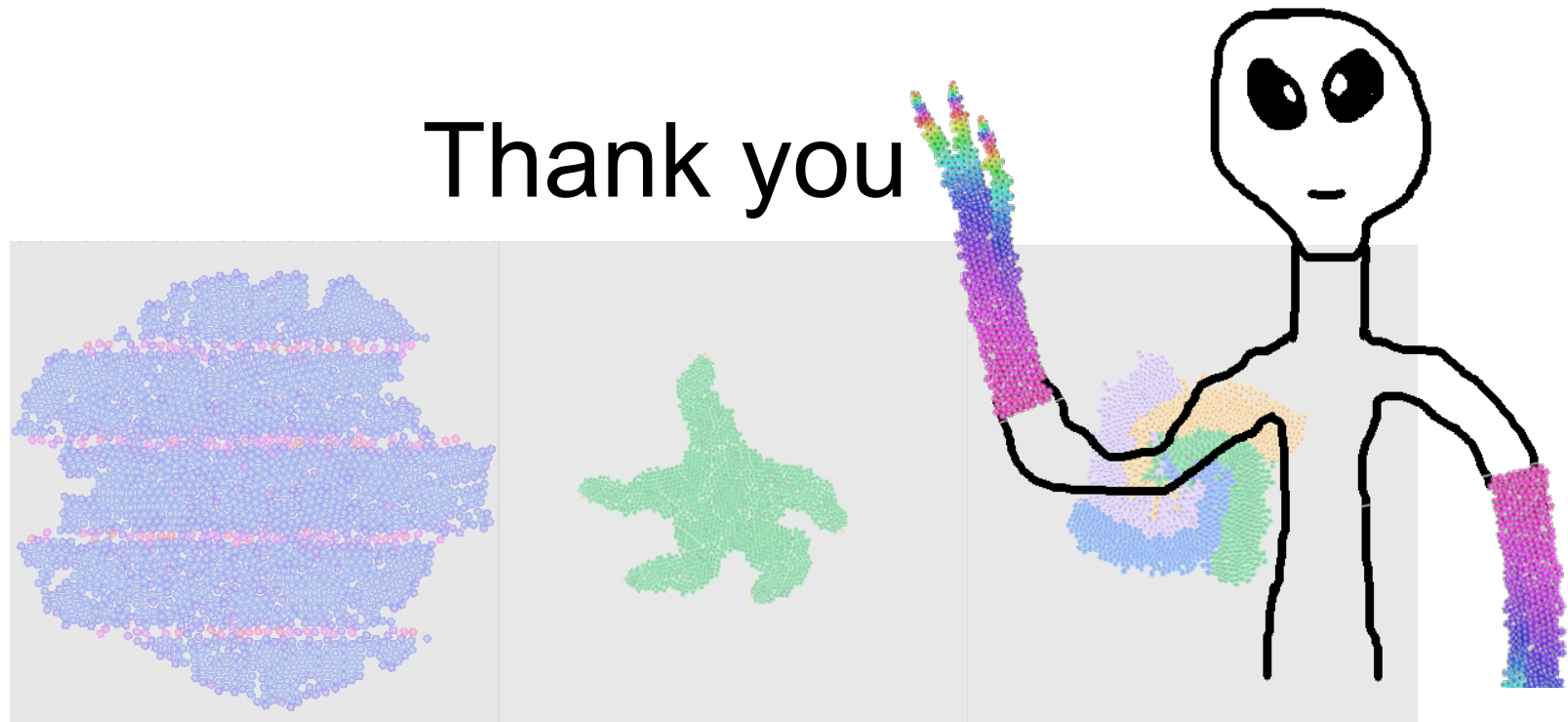


- Merge our virtual cell model and our morphogenesis approach
- Use more deeply our morphogenesis model ...
- And also study backward morphogenesis





# Thank you



A. Jeannin-Girardon et al, IEEE/ACM Transactions on Computational Biology and Bioinformatics (TCBB), 2015

A. Sarr et al, 3rd international conference on Theory and Practice of Natural Computing (TPNC), 2014

# Questions?



Vincent, why did you do that ?

- Imagine, we integrate in our cells just a part of the works presented in cBio 2015...
- We would see, for example, tumor growth taking into account genes, pathways, etc.
- We would predict the effect of radiotherapies, surgical acts, etc.



A. Jeannin-Girardon et Al, IEEE/ACM Transactions on Computational Biology and Bioinformatics (TCBB), 2015  
A. Sarr et Al, 3rd international conference on Theory and Practice of Natural Computing (TPNC), 2014