

Multi-Agents Systems and environment modelling...

**NetBioDyn,
an easy to use multi-agents engine
for ecosystems simulation**

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Road map

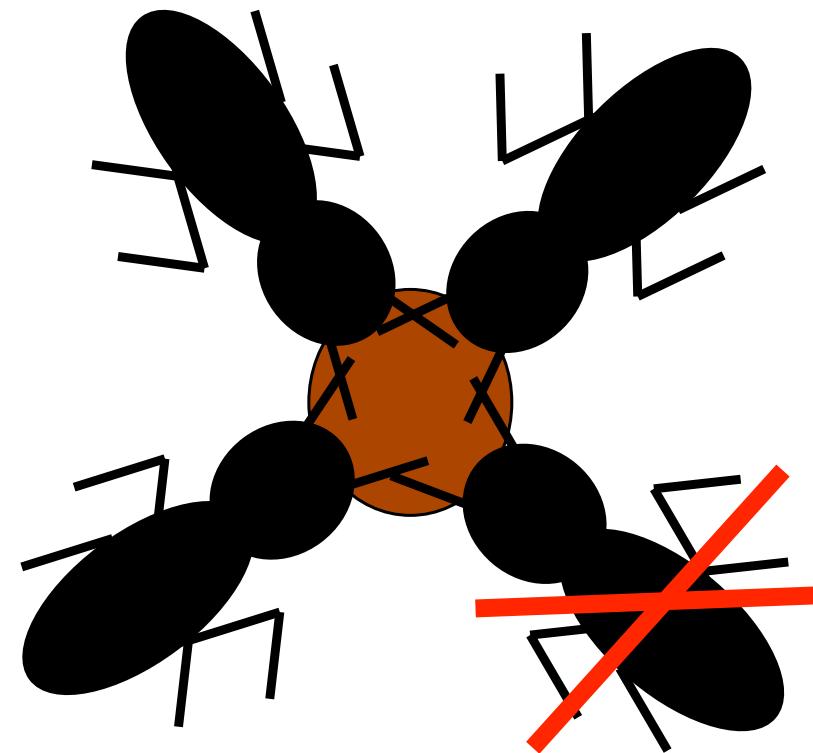
- Multi-Agents Systems (MAS)
- From Biological environment simulation
- Towards Ecosystems simulation
- NetBioDyn software
- Conclusions and futur works

Multi-Agents systems properties

Agent : perception-decision-action

Multi-agents System :

- auto-organisation
- emergence
- robustness
- adaptability

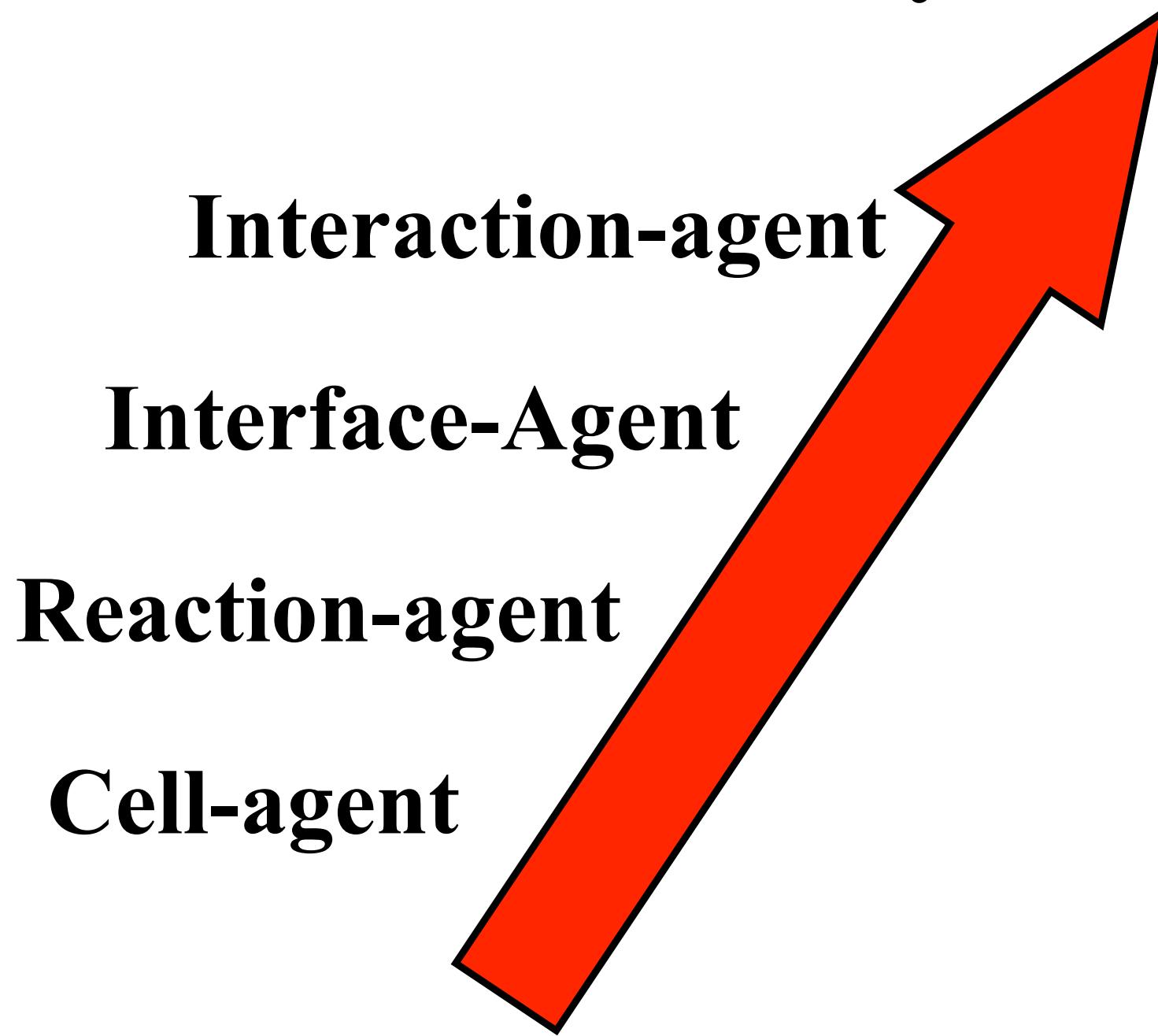


Road map

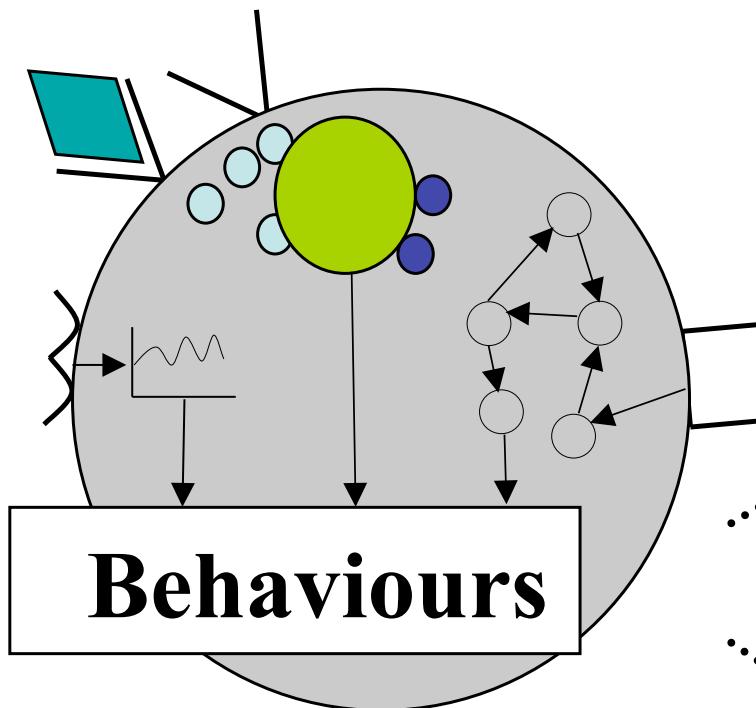
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Multi-Agent Systems and Biological modelling & simulation

From cell-agent
To systemic approach



Cell-agent model



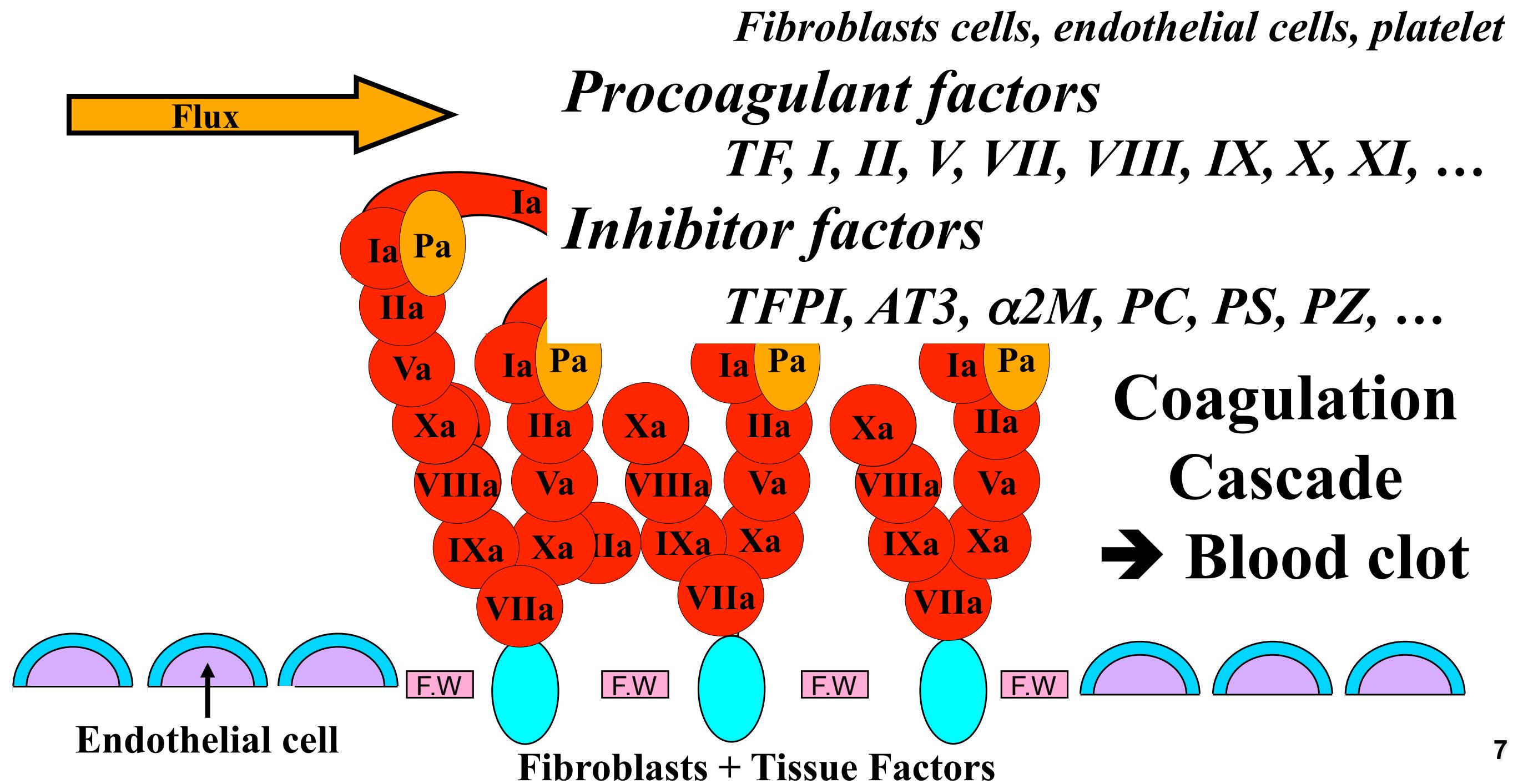
Basic behaviours

- Mitosis
- Activation
- Internalisation
- Expression of receptor
- Apoptose

Model of **located agents** with complex behaviors

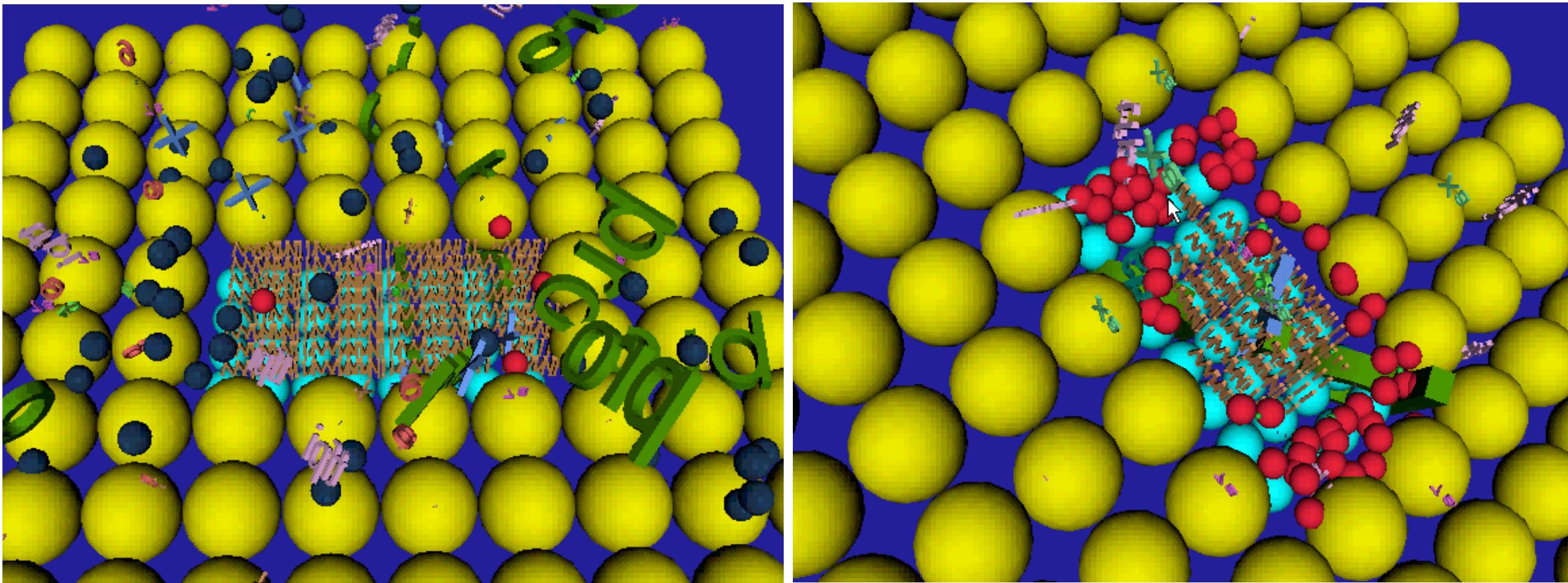
Cell-agent model: An exemple of application

Simulation of physiologic coagulation: *Cell*



Cell-agent model: An exemple of application

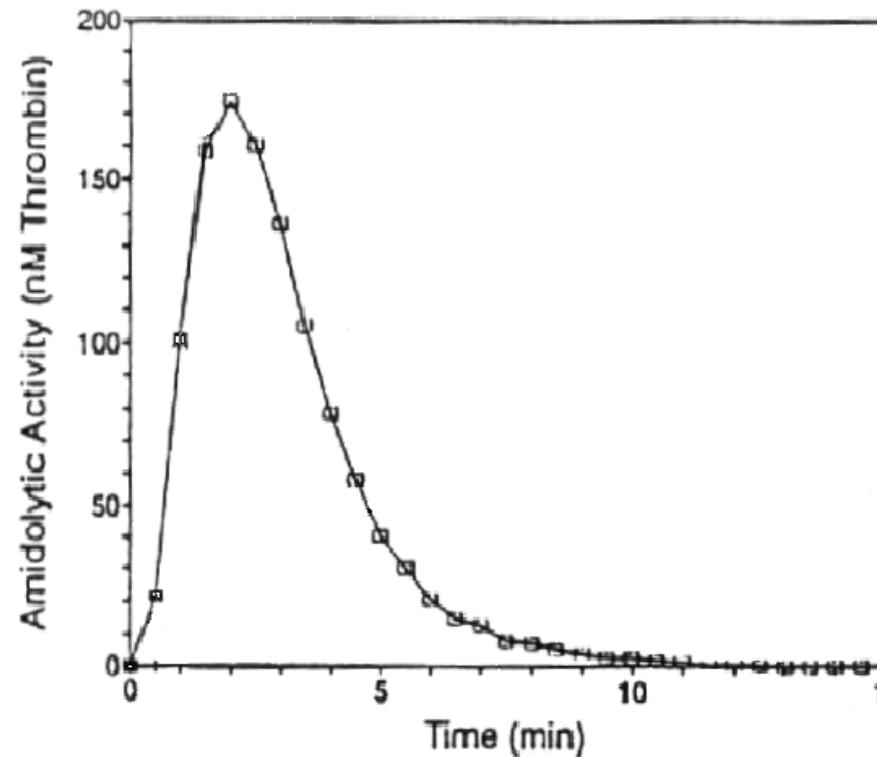
Simulation of physiologic coagulation: → blood clot...



Cell-agent model: An exemple of application

Elements of validation of the coagulation multiagents model :

- Comparison with Biological experiment



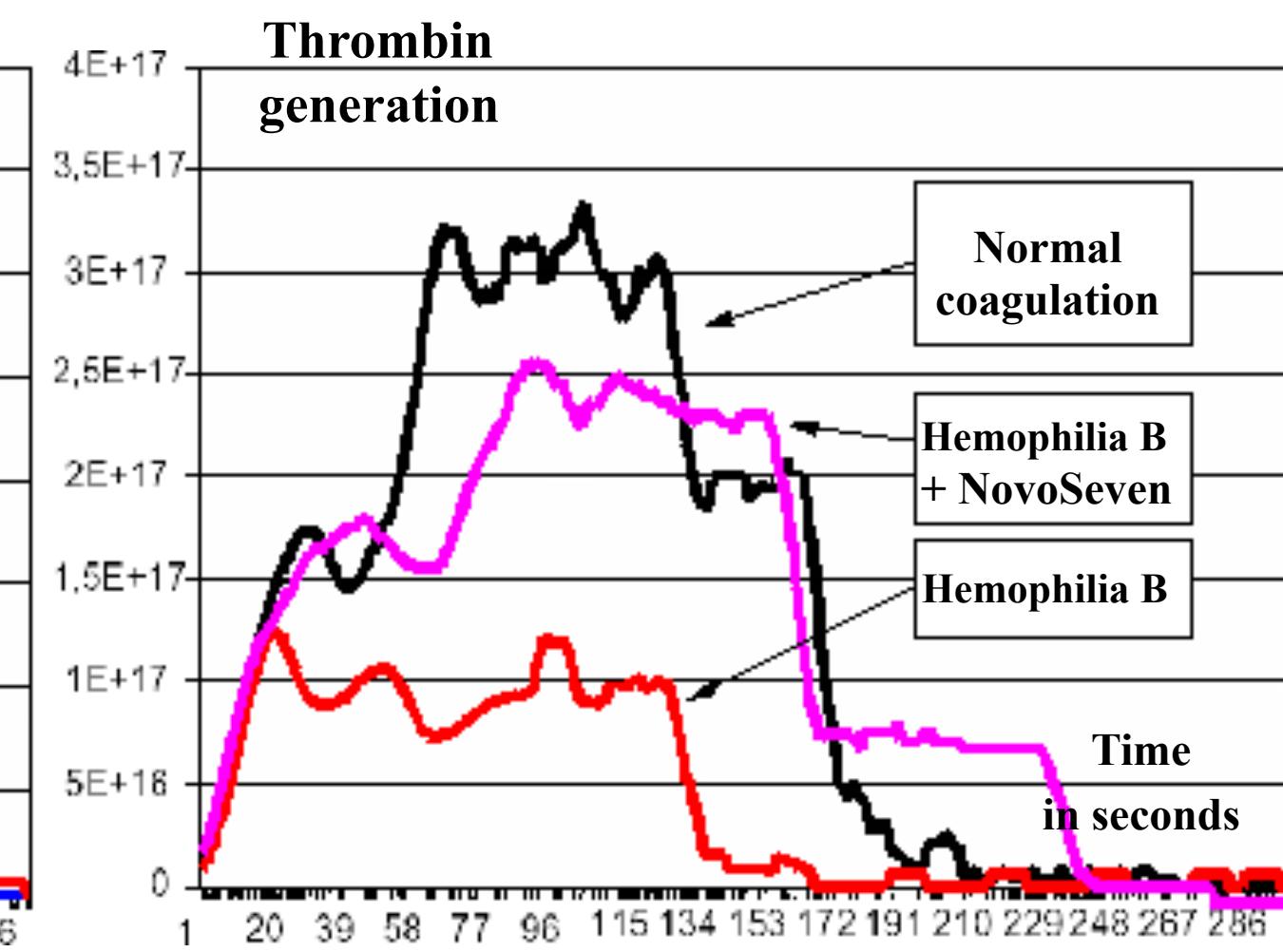
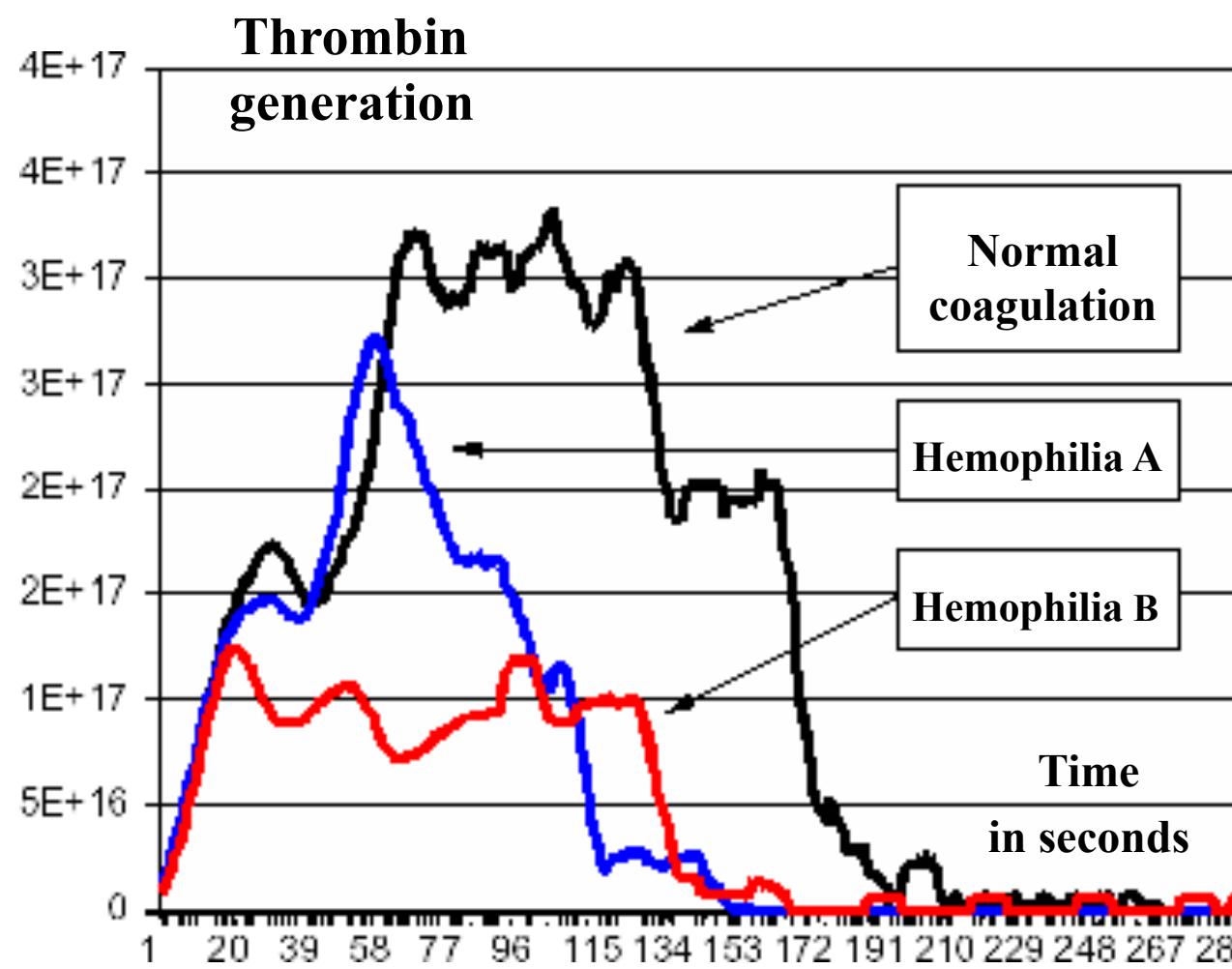
Curve of thrombin
Generation
[Hemker, 1995]

- Coherence with respect to pathologies

Cell-agent model: An exemple of application

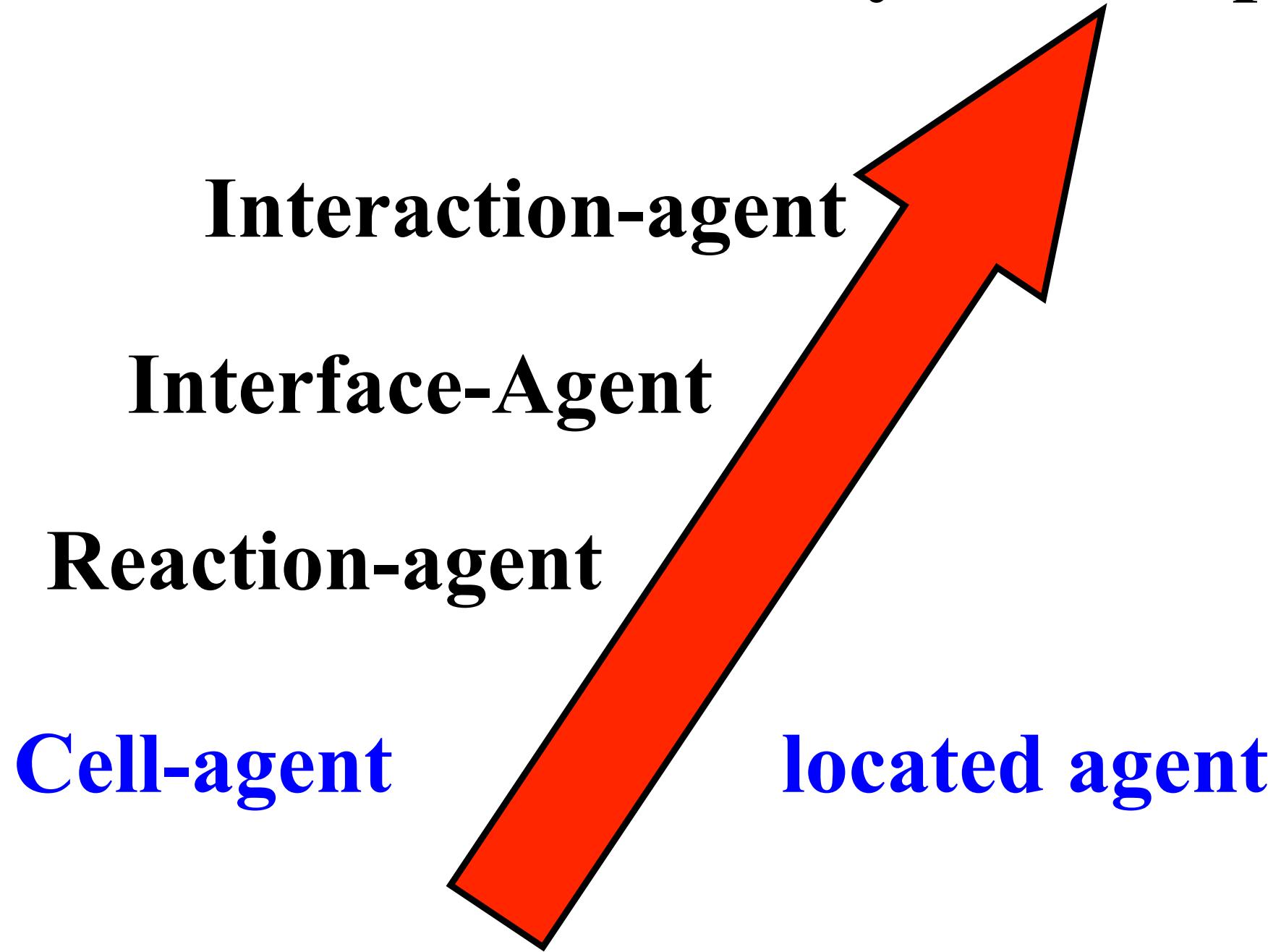
Simulation of physiologic coagulation:

Healthy patient, hemophiliac, hemophiliac with treatment



Multi-Agent Systems and Biological modelling & simulation

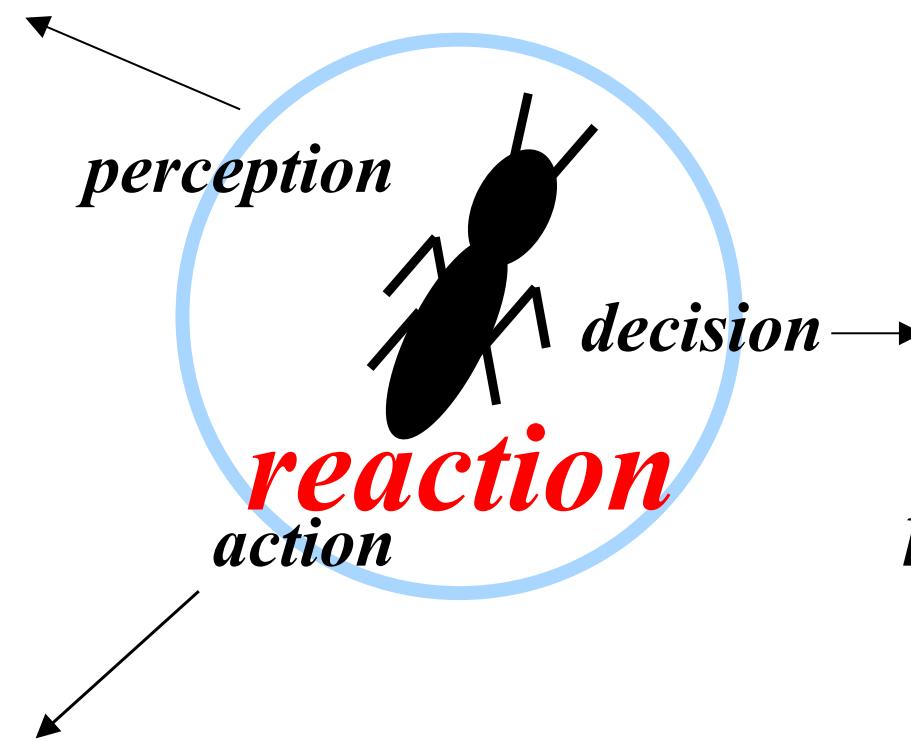
From cell-agent
To systemic approach



Reaction-agent model

- « microscopic » level : *agent = cell/molecule*
- « macroscopic » level : *agent = reaction*

*1: reading of the concentrations
in reactants*



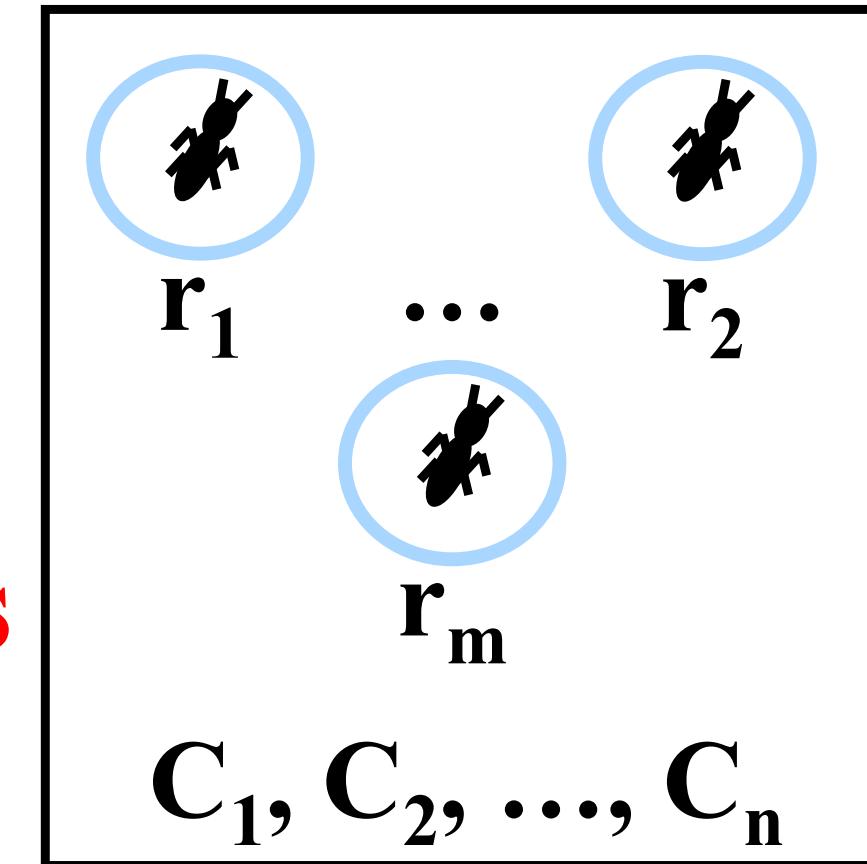
*2: calculation the
reaction speed and
then the quantity of
reactant to be reacted*

*3: consequently, modification of the
concentrations in reactants and products*

Reaction-agent model

Spatial
indiscernibility

Non located agents



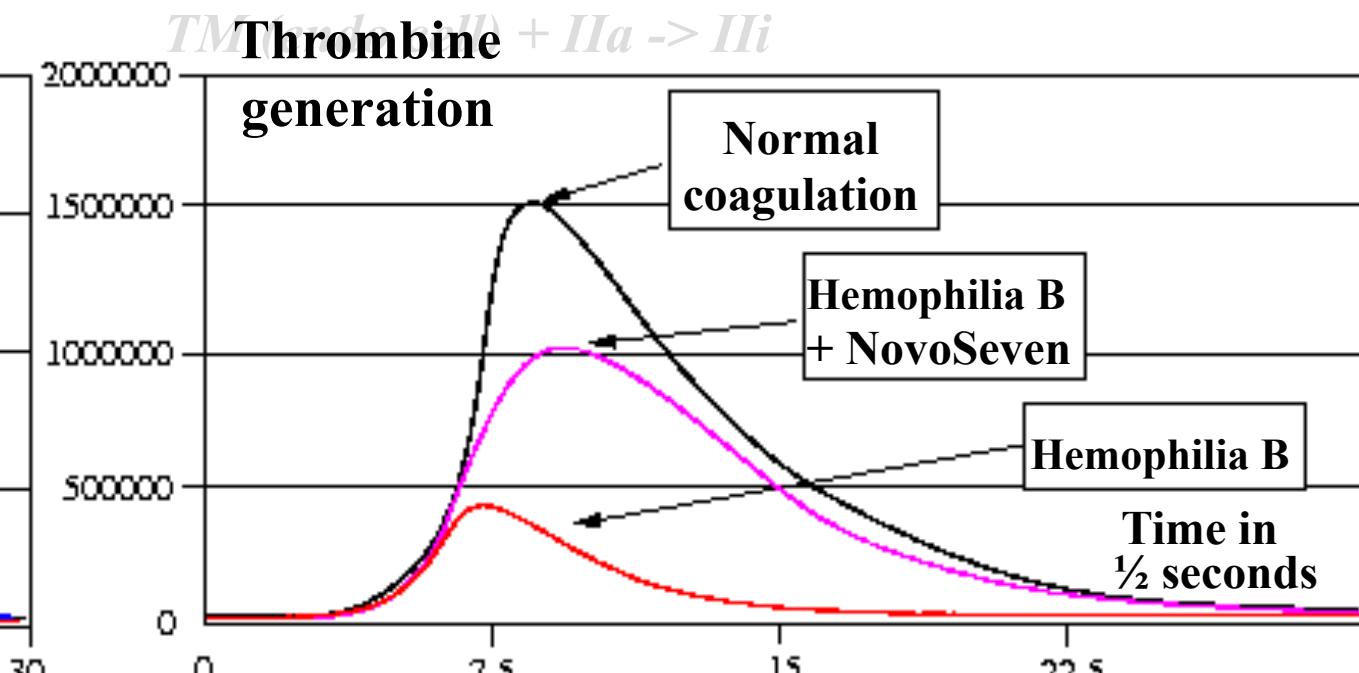
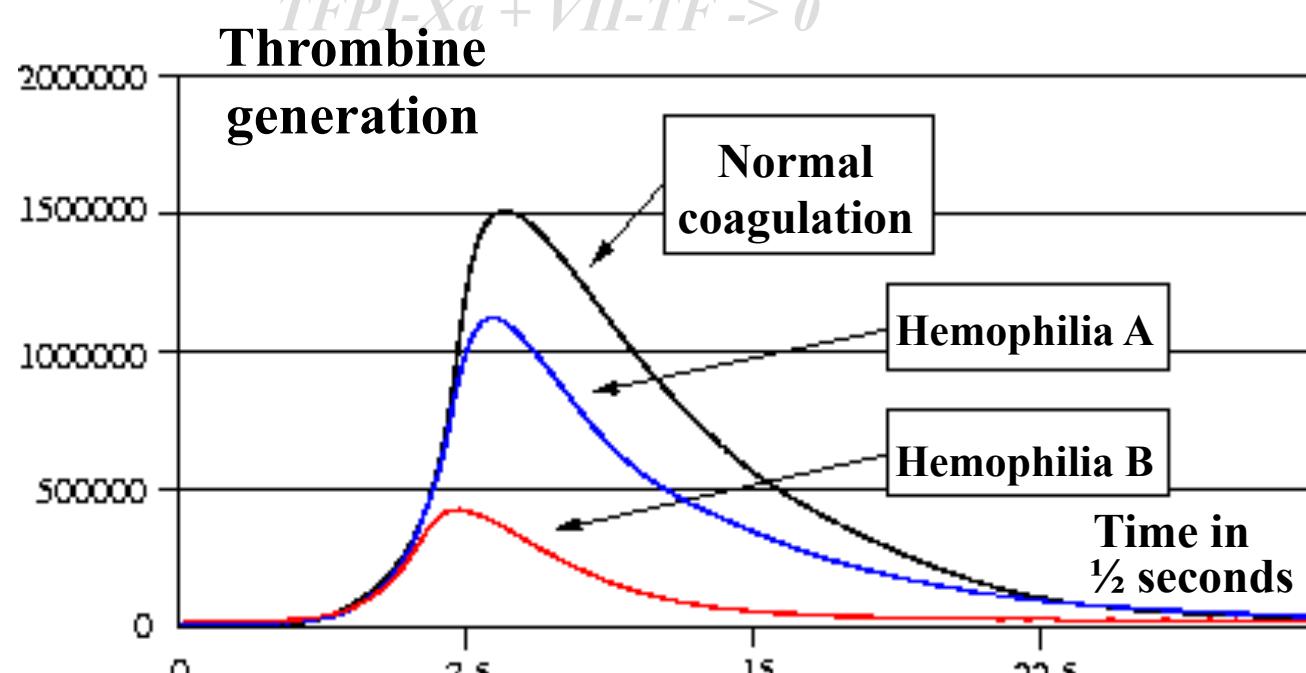
Chemical reactor

- Asynchronous phenomena and chaotic order
- No Ordinary Differential Equation

Reaction-agent model: An exemple of application



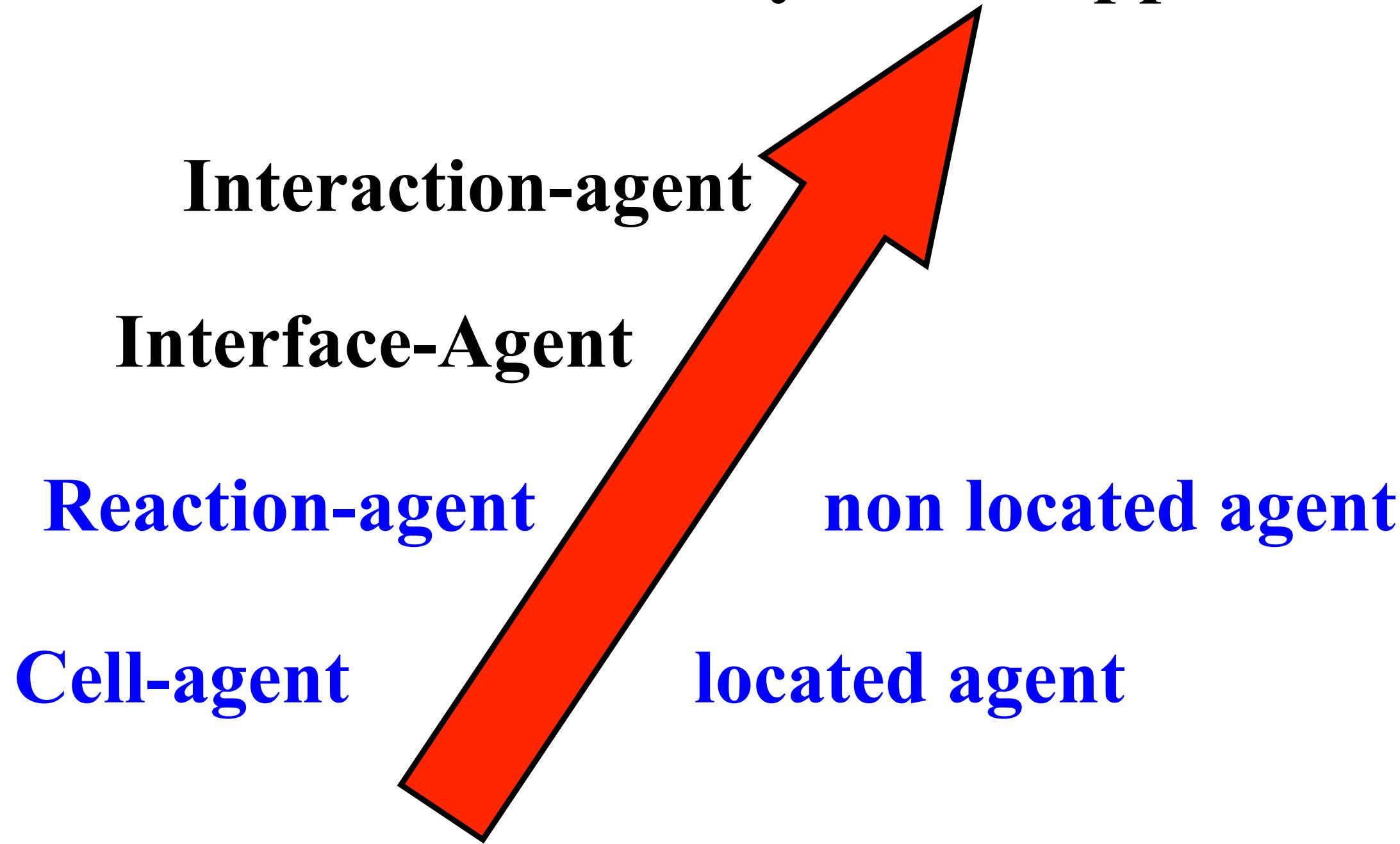
Simulation of physiologic coagulation:



42 reactions

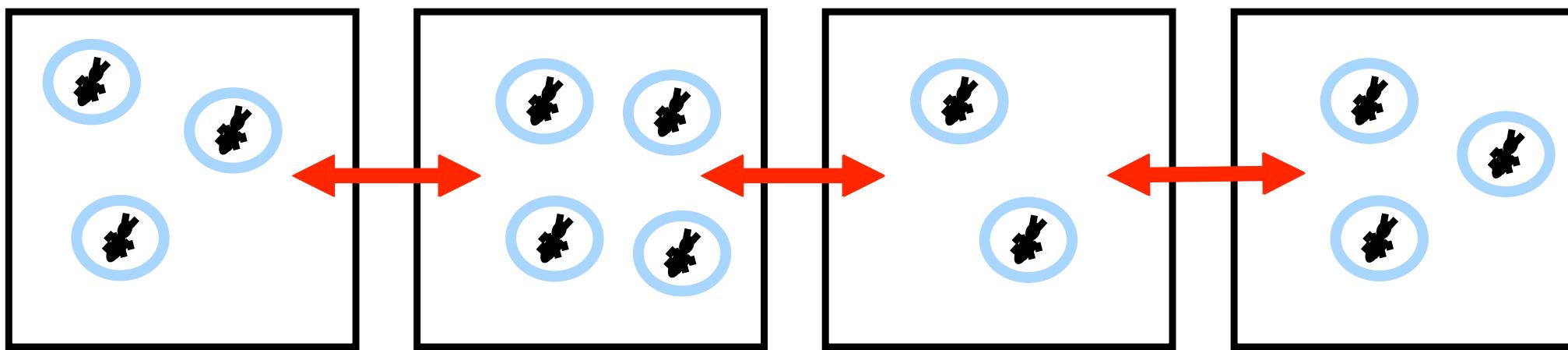
Multi-Agent Systems and Biological modelling & simulation

From cell-agent
To systemic approach



Interface-agent model

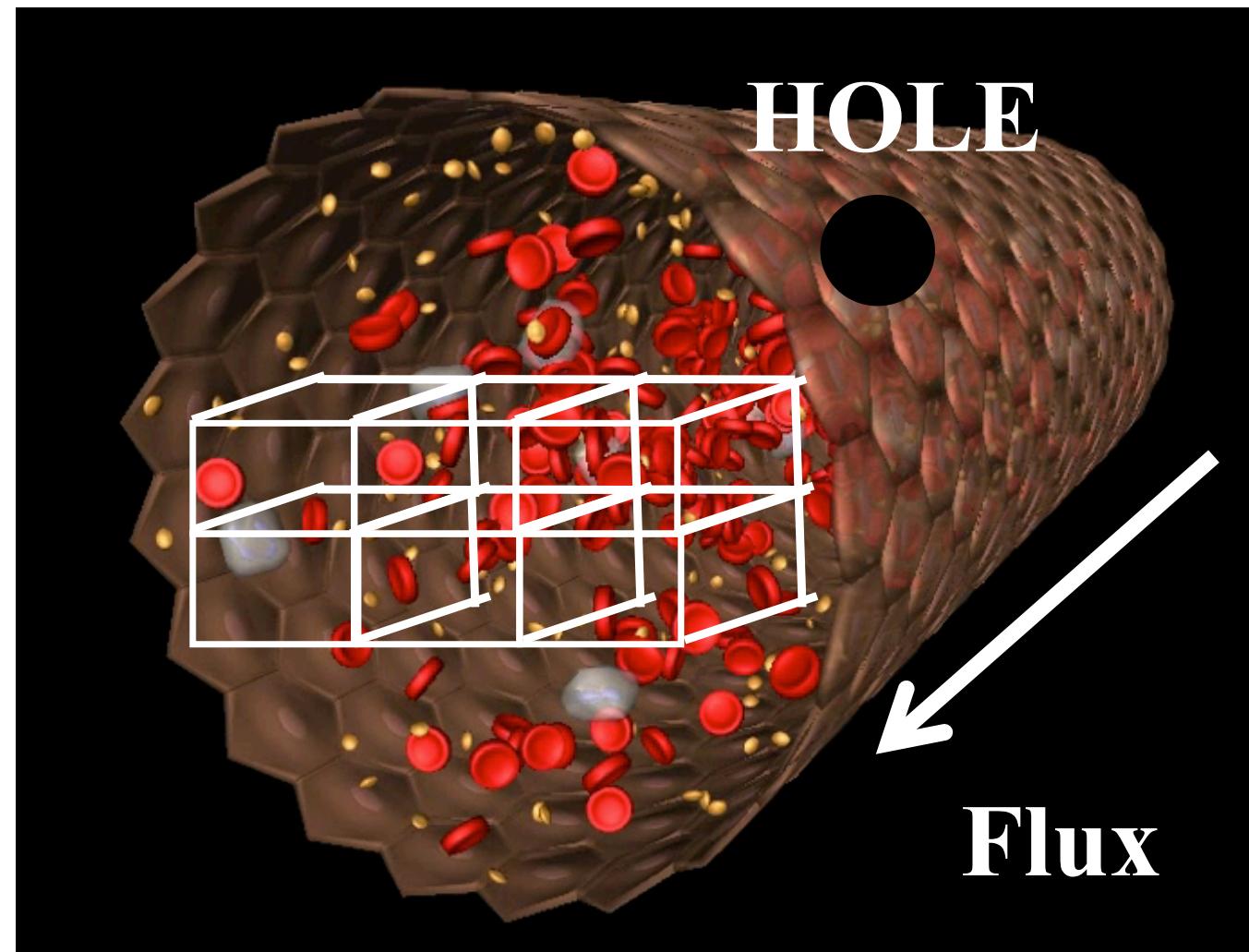
An « agent » point of view:



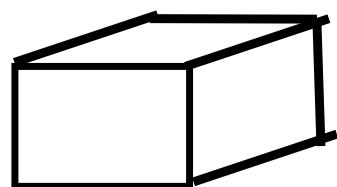
- Interface-agent
- interaction between the mediums
- Asynchronous phenomena and chaotic order
- No Partial Differential Equation

Interface-agent model: An exemple of application

Coagulation :



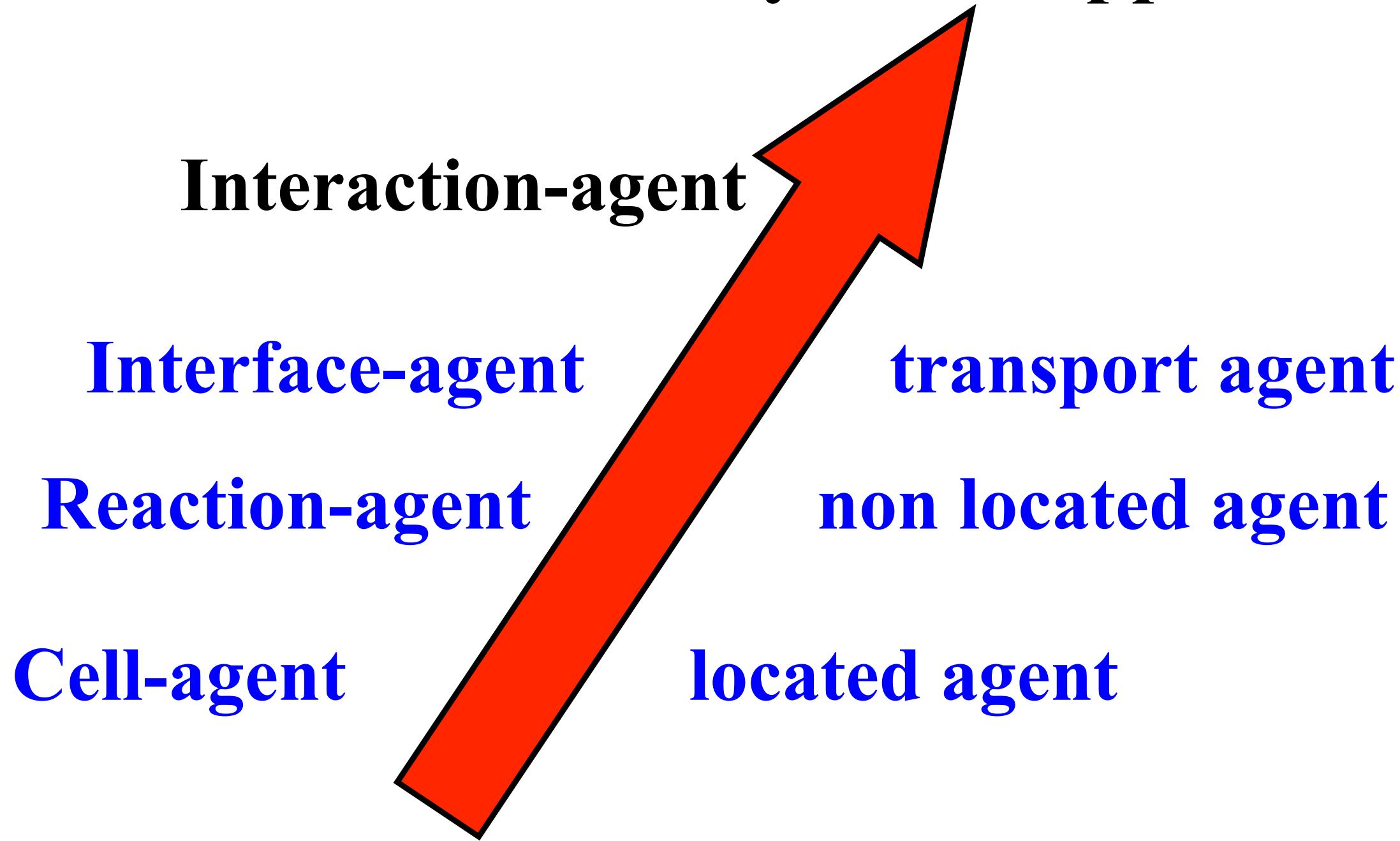
3D Vessel



Chemical Reactors : 42 reactions (coagulation)

Multi-Agent Systems and Biological modelling & simulation

From cell-agent
To systemic approach

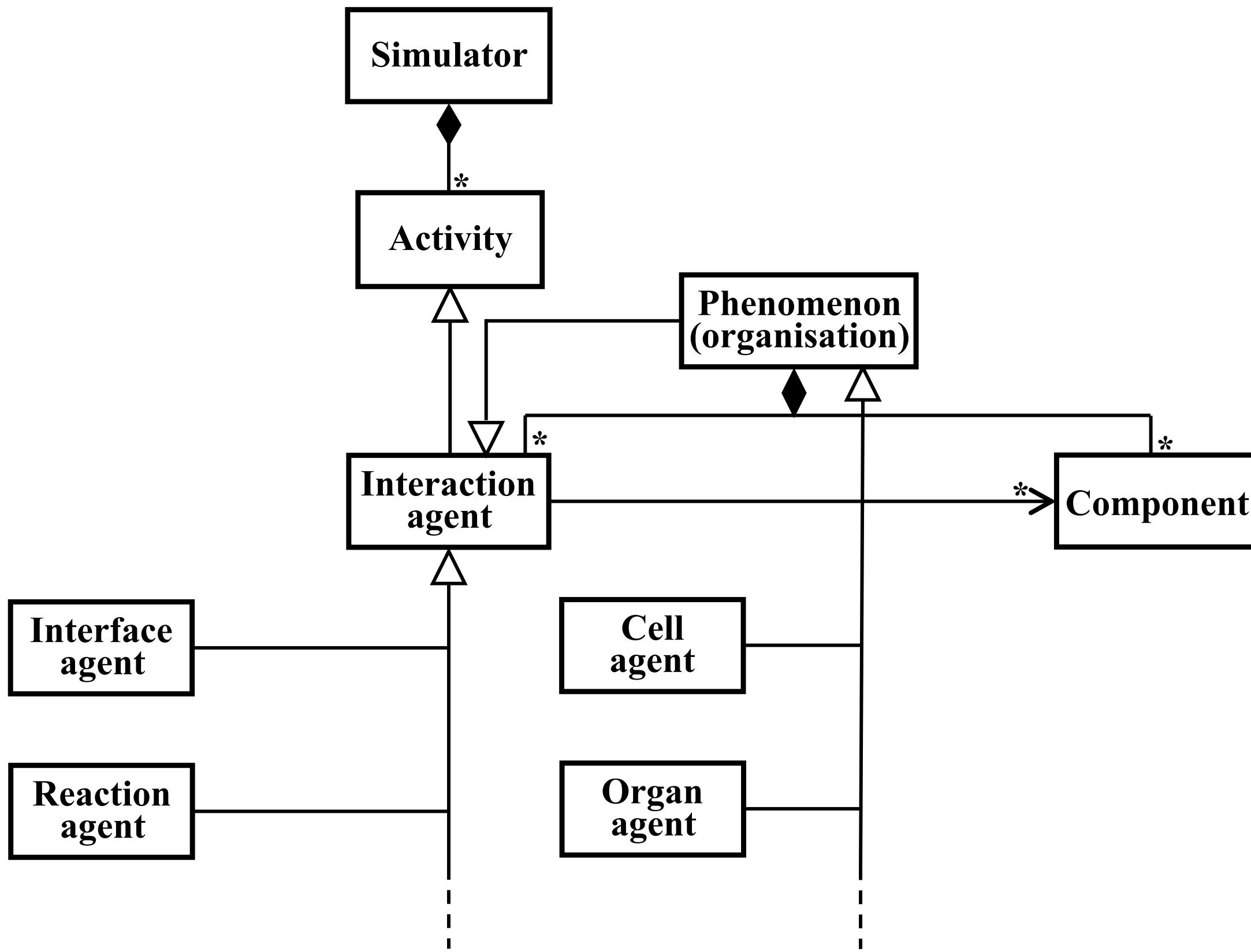


Generic model of interaction-agent

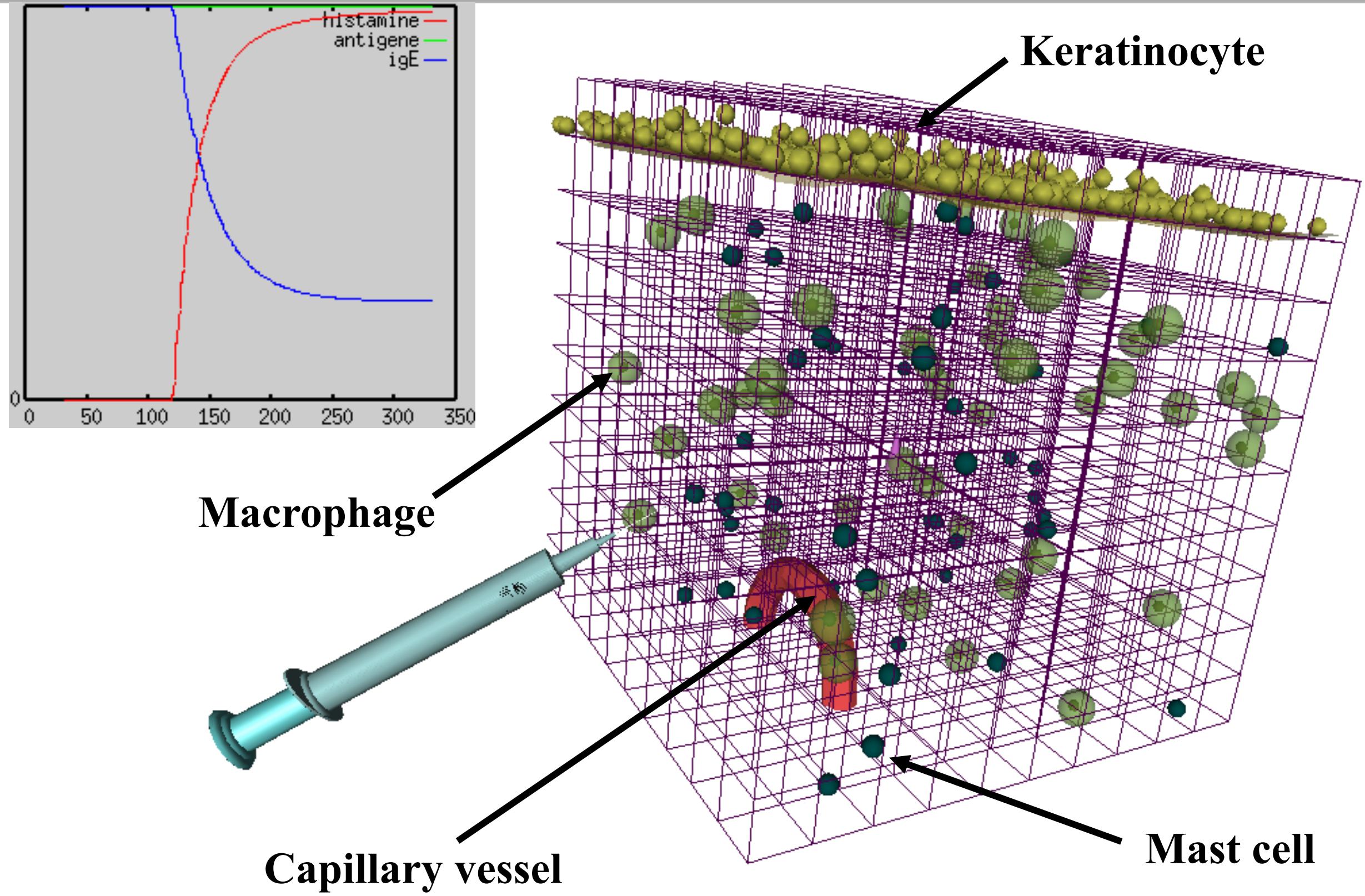
Main principle :
Models' autonomy

- Interaction between models
of different natures
- Multi-modeling Simulation
- Systemic paradigm
- Data Matter exchange
between organisations

Generic model of interaction-agent

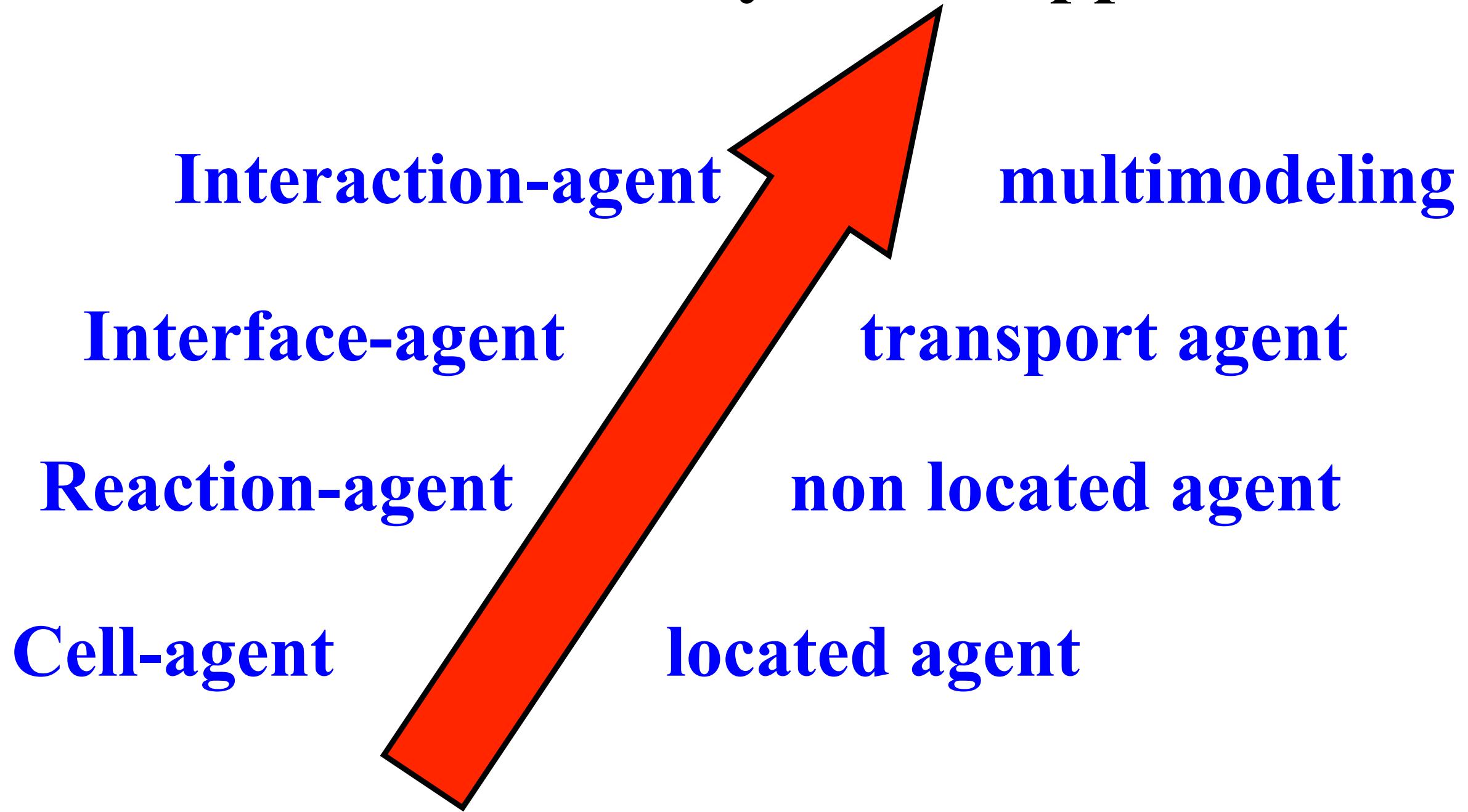


Generic model of interaction-agent : An exemple of application



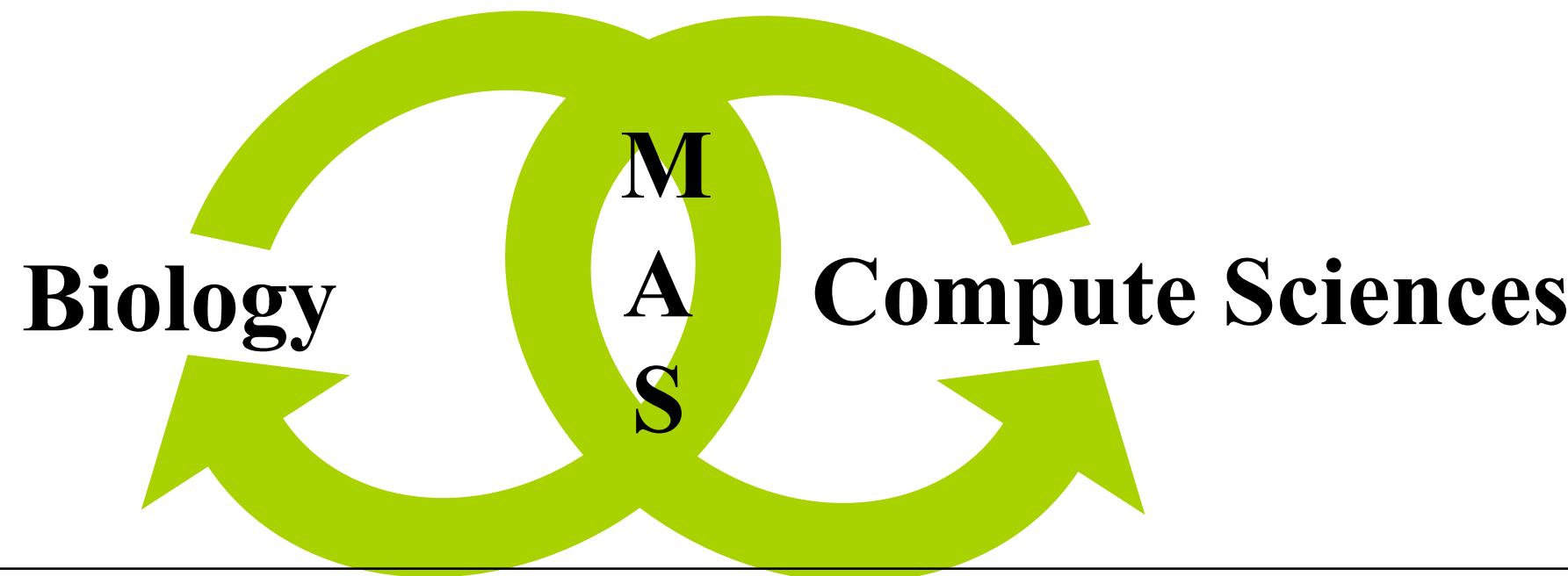
Multi-Agent Systems and Biological modelling & simulation

From cell-agent
To systemic approach



Interests in the field of biology

- To help the reflection
 - ▶ Test and validate hypotheses
 - ▶ Analyse parameters influence
 - ▶ Understand complex phenomena
- To prepare experiments
- To accelerate the drug discovery



Road map

- Multi-Agents Systems (MAS)
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- NetBioDyn software
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Towards Ecosystems simulation

Cells → Entities (insects, etc.)

&

Low level interaction

Reaction → High level interaction
between entities

Interface/Interaction → Physical environment

Road map

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NetBioDyn software : an easy to use multi-agents engine

Goal:

Rapid prototyping of
biological & ecosystem simulations

<http://virtulab.univ-brest.fr/netbiodyn.html>

<http://virtulab.univ-brest.fr/netbiodyn3D.html>

NetBioDyn software : an easy to use multi-agents engine

Key concepts:

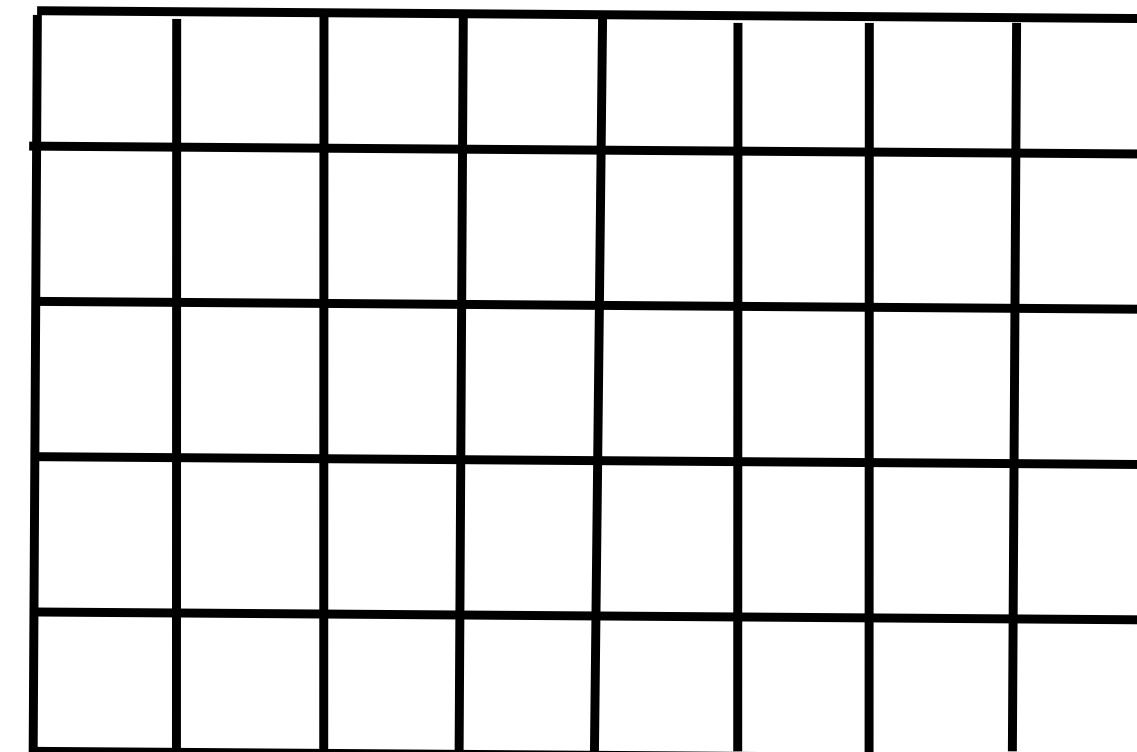
- ➔ Environment: a grid
- ➔ Entities: colored squares
- ➔ Interaction with environment : simple rules
- ➔ Interaction between entities : simple rules

Easy to use... No programming skill requires !!!!

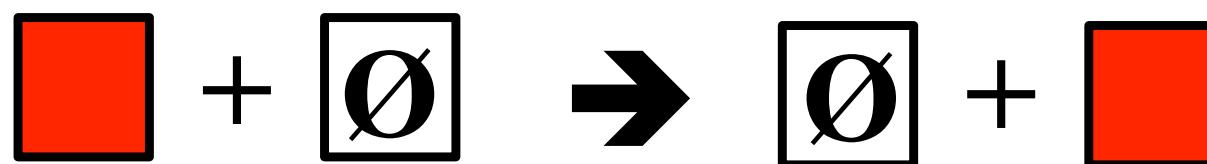
NetBioDyn software : How to model...?

1st : take a grid

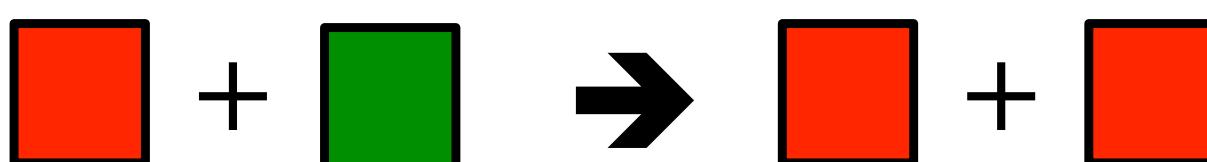
2nd : decide which entities to use



3rd : define rules (with a probability of activation) to give entities movements and interactions



P=1 (go to the right)

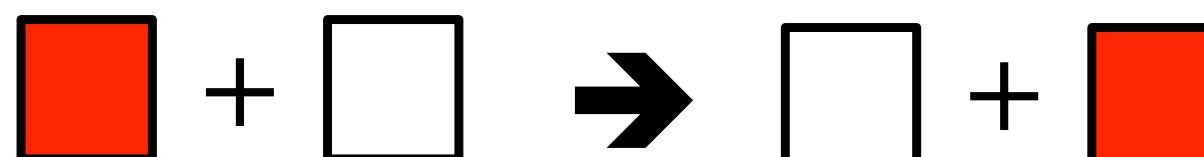
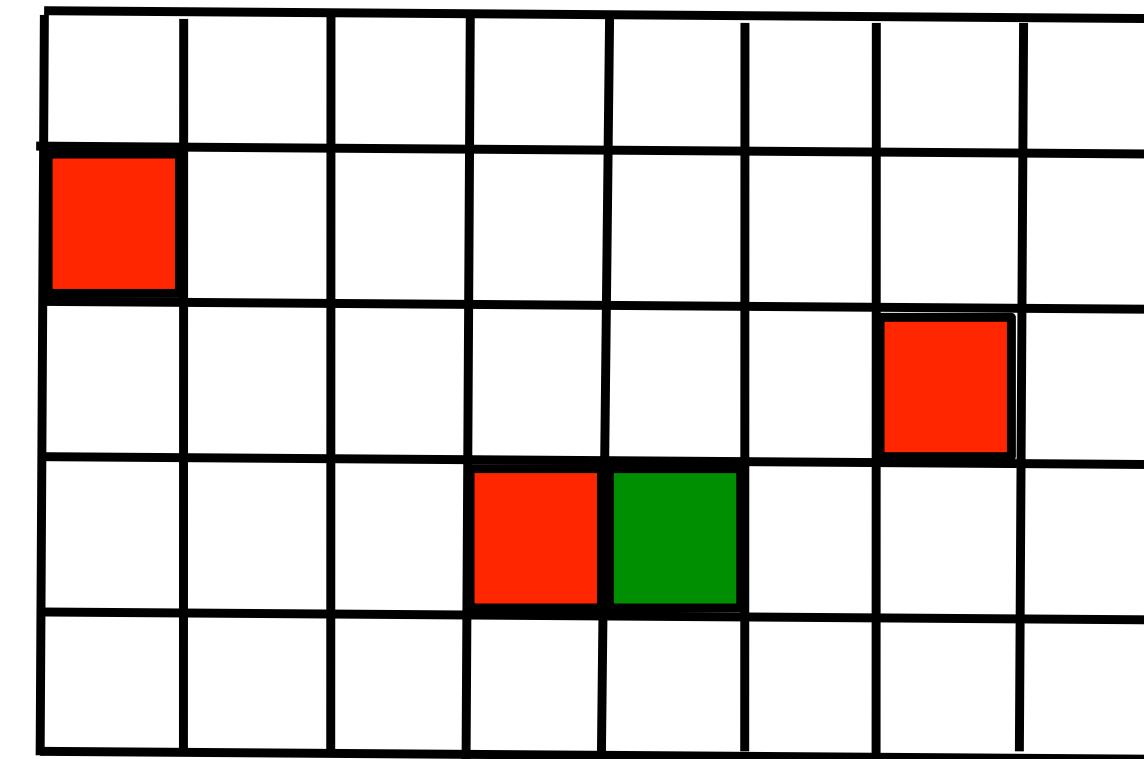


P=0.5 (contamination)

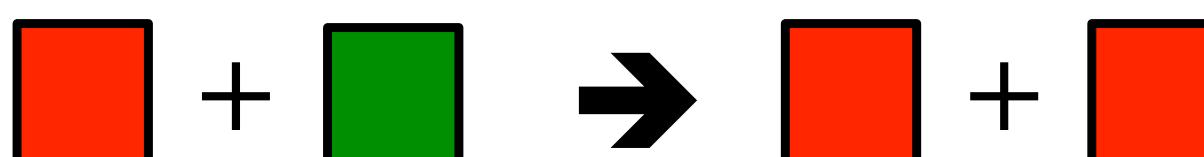
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NetBioDyn software : How to model...?

4th : place entities
and : run ➤



(go to the right)

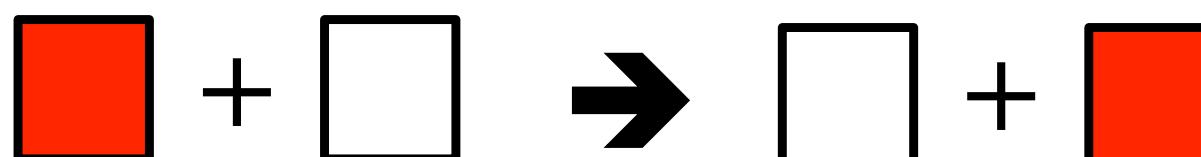
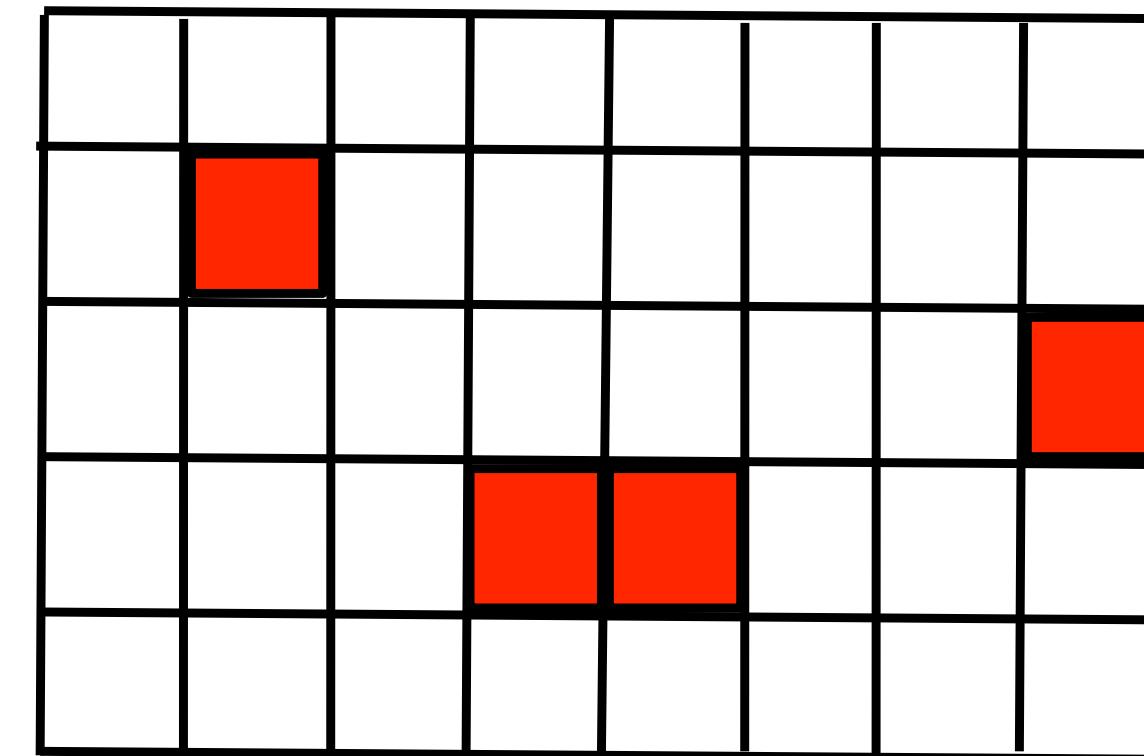
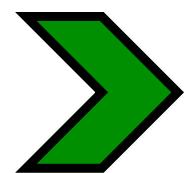


(contamination)

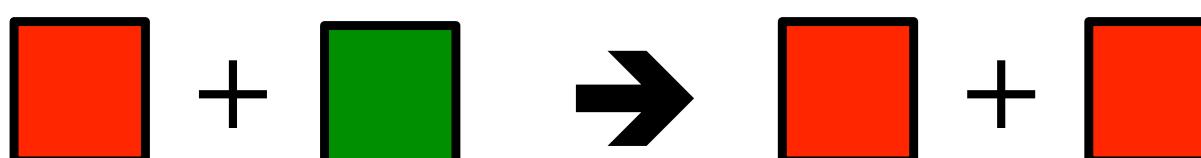
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NetBioDyn software : How to model...?

4th : place entities
and : run



(go to the right)

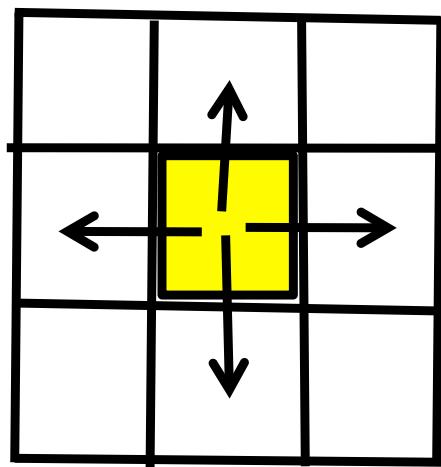
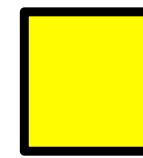


(contamination)

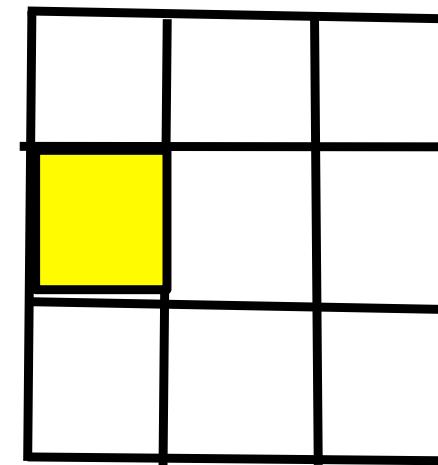
.....

NetBioDyn : 1st example, randomwalk

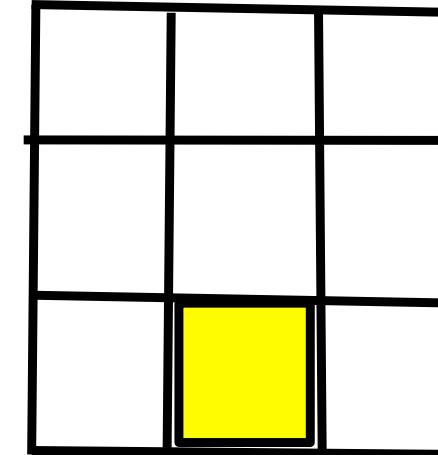
→ Entities:



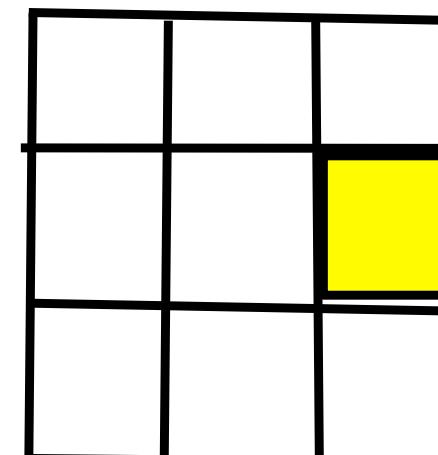
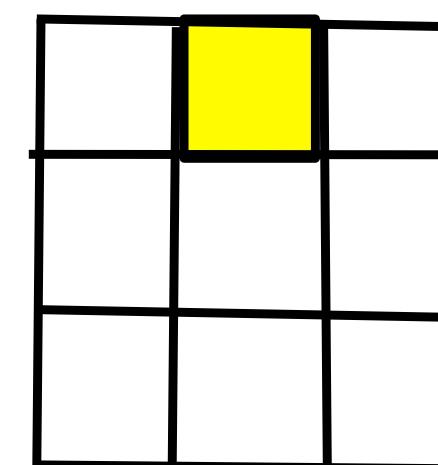
Rd_Walk
→
P=1



or

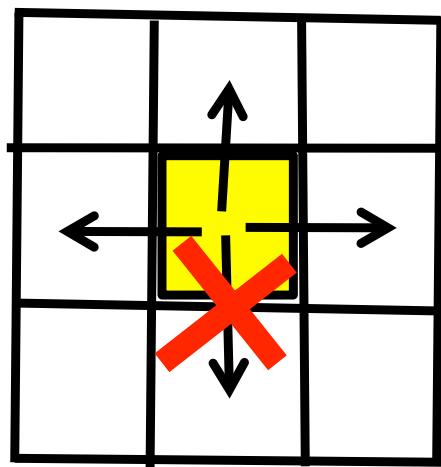
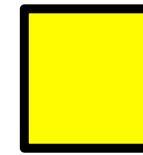


or

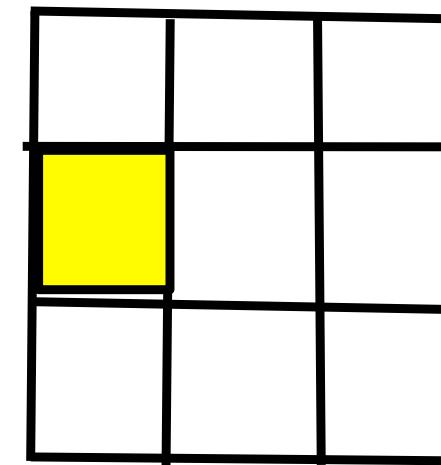
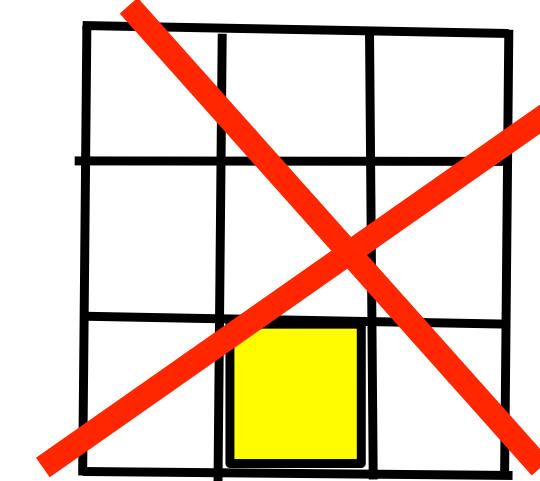


NetBioDyn : 1st example, randomwalk

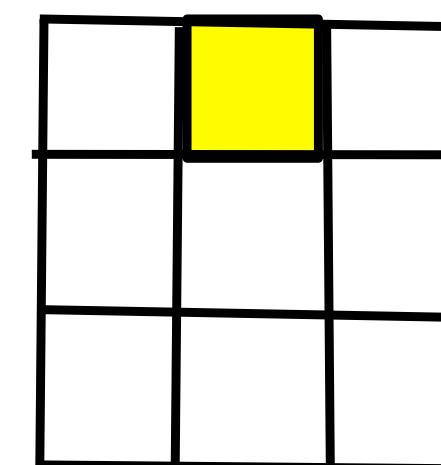
→ Entities:



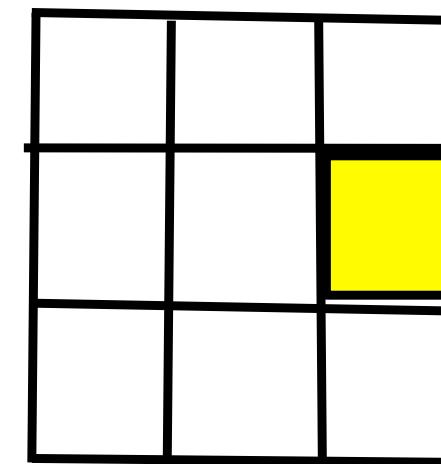
Rd_Walk
→
P=1



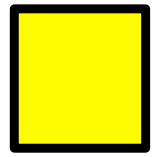
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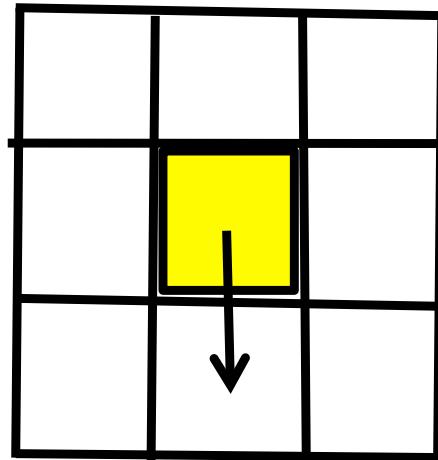


or

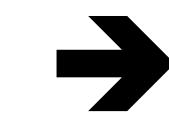


NetBioDyn : 2nd example, sandglass

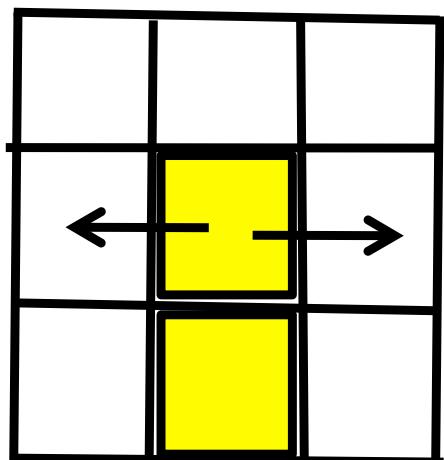
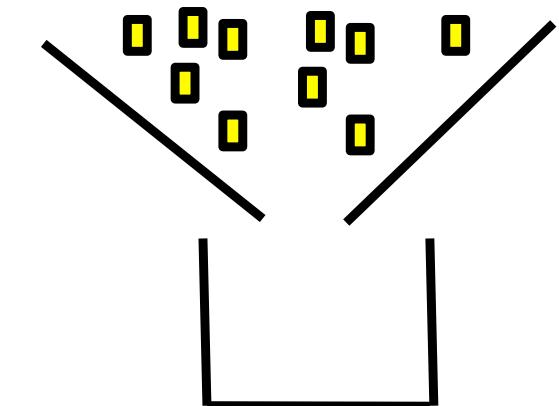
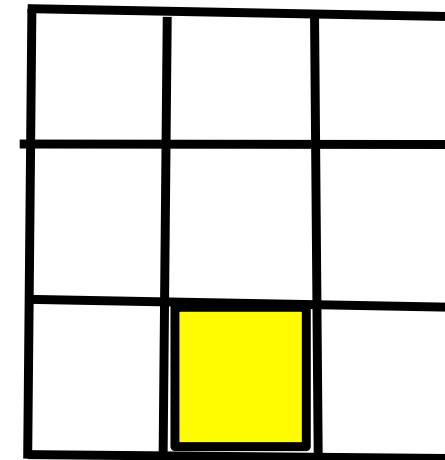
→ Entities: grain  and border 



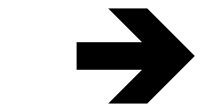
Go_Down



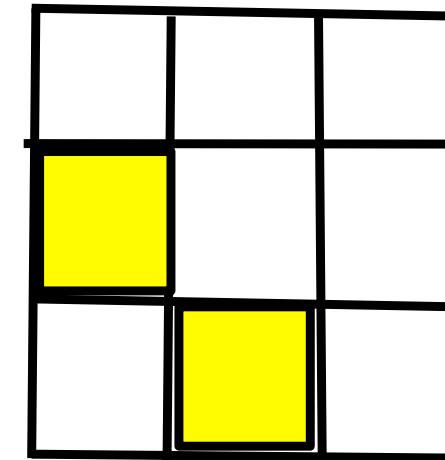
P=1



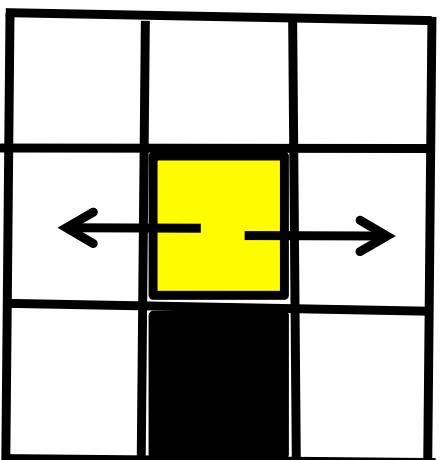
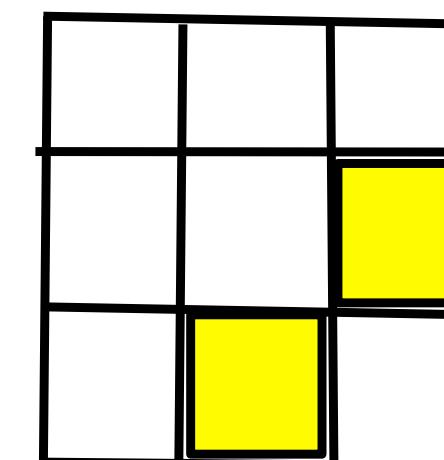
Go_LeftRight



P=0.5



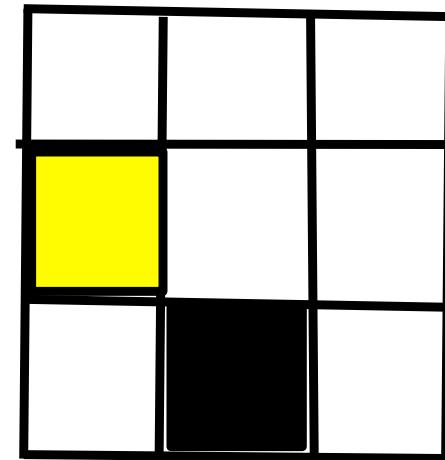
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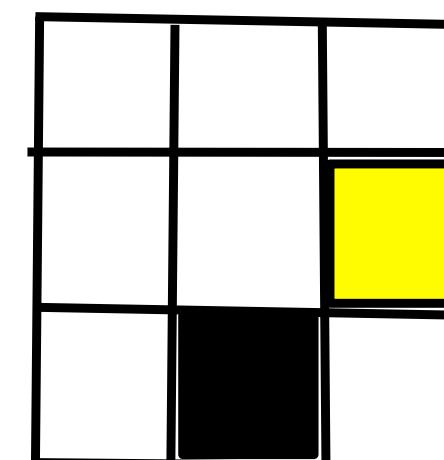
Go_Border



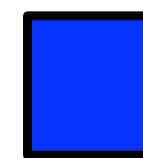
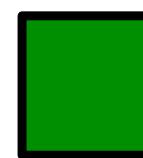
P=0.75

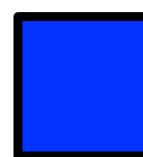


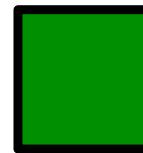
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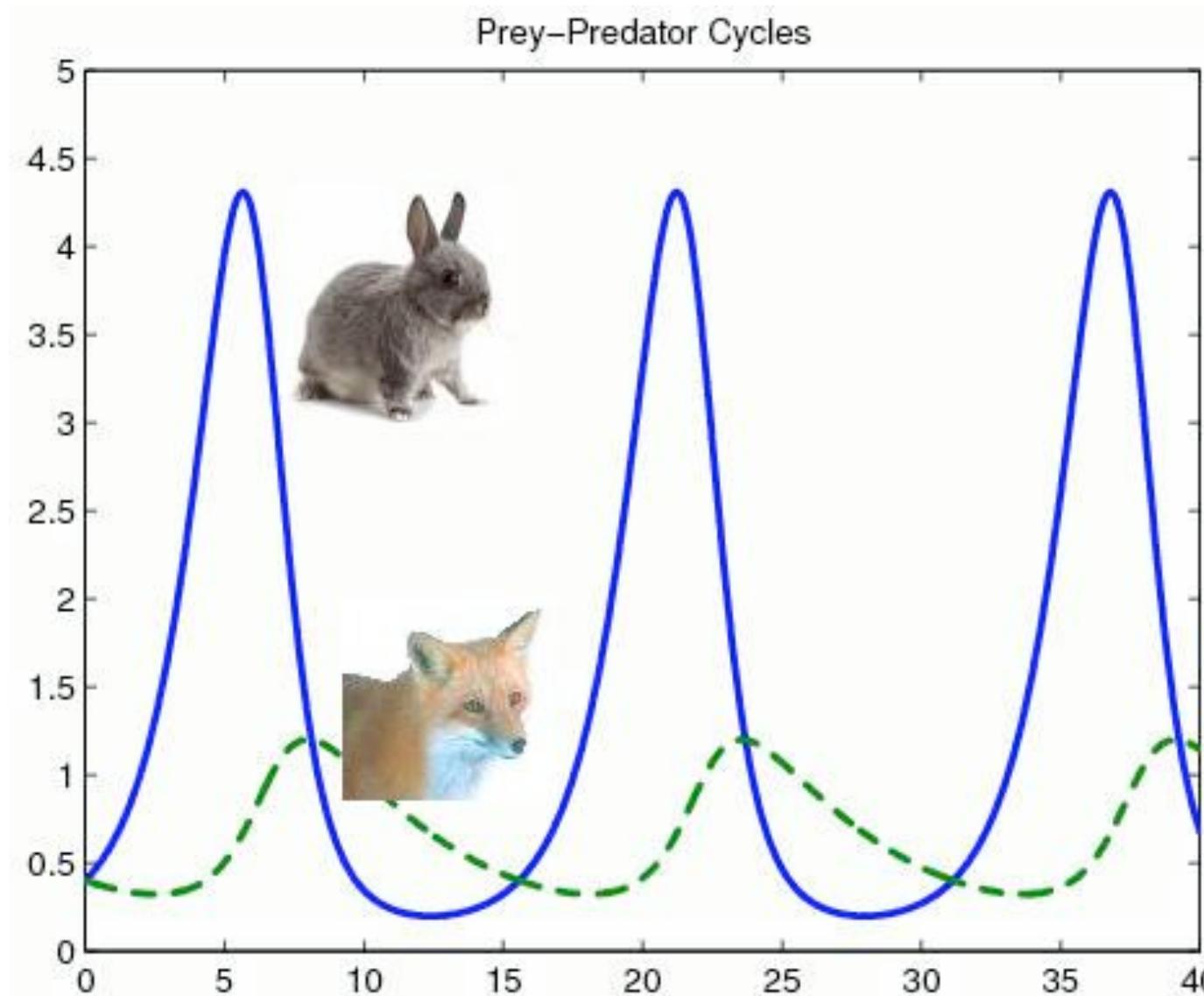


NetBioDyn : 3rd example, prey-predator

→ Entities: prey  and predator 

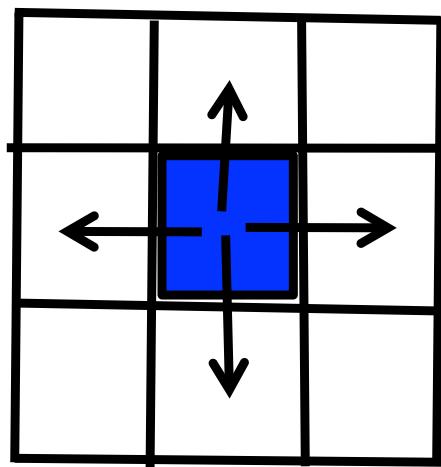
Prey  $\frac{1}{2}$ life time : 2000 cycles + **Rd_Walk**

Predator  $\frac{1}{2}$ life time : 200 cycles + **Rd_Walk**

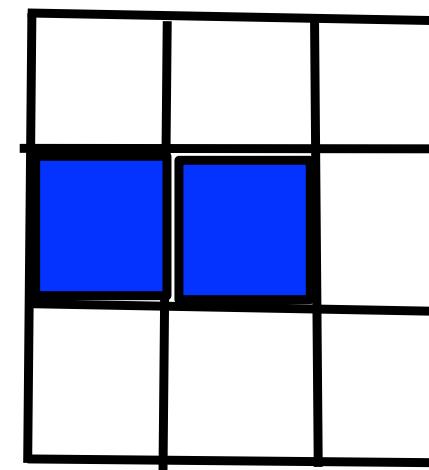


NetBioDyn : 3rd example, prey-predator

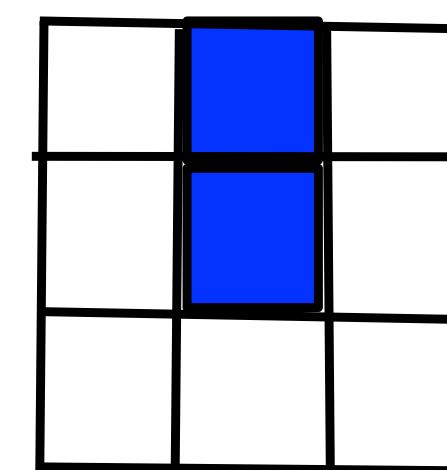
→ Entities: prey  and predator 



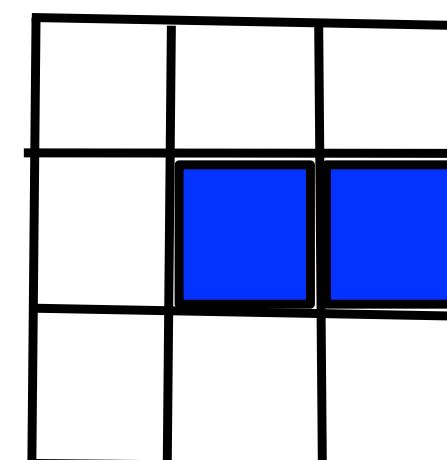
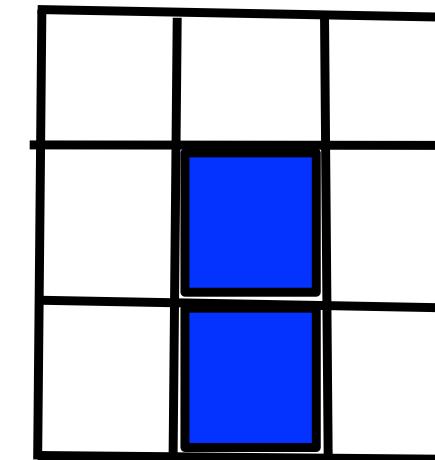
Prey Birth
 \rightarrow
 $P=0.01$



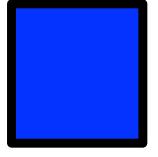
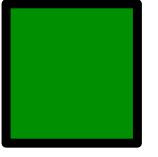
or



or



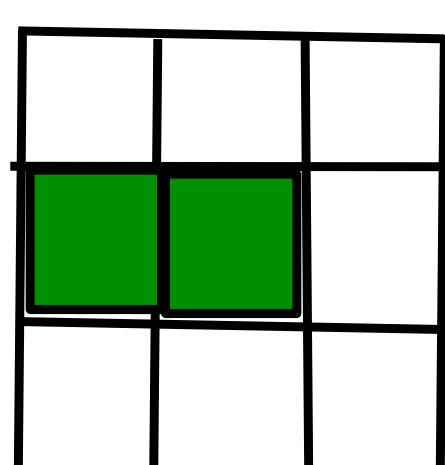
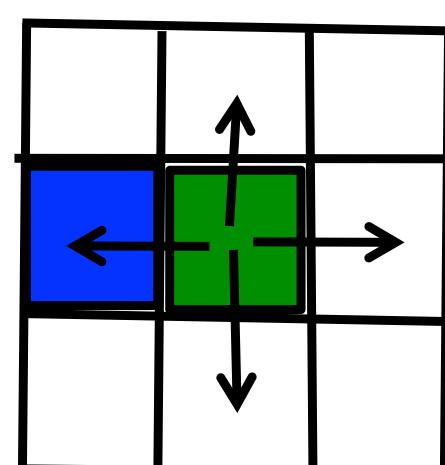
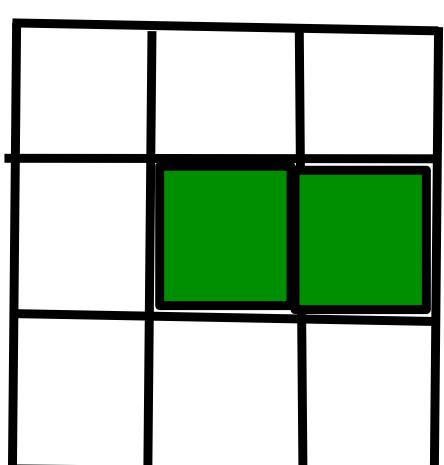
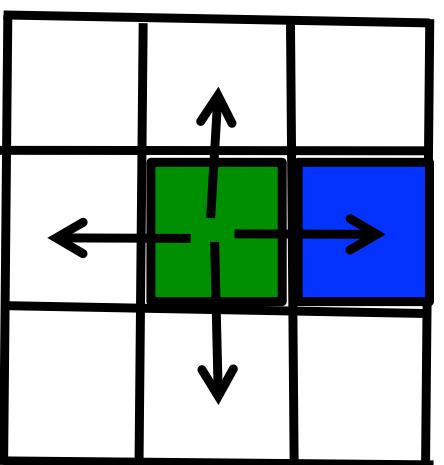
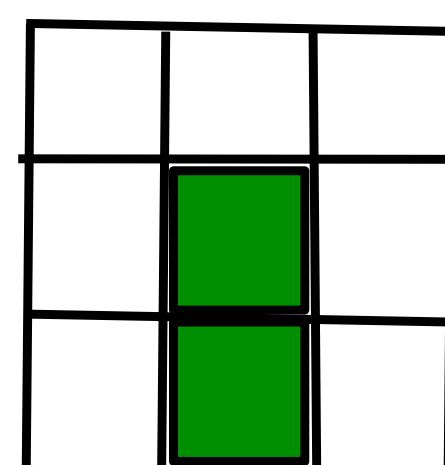
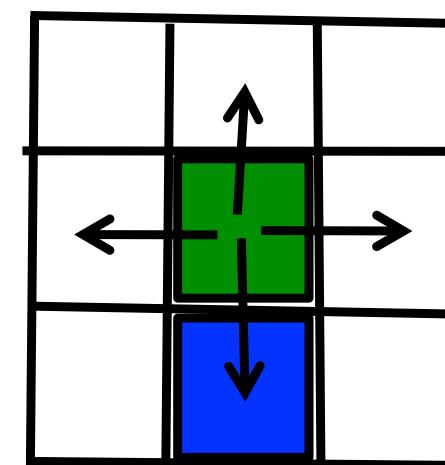
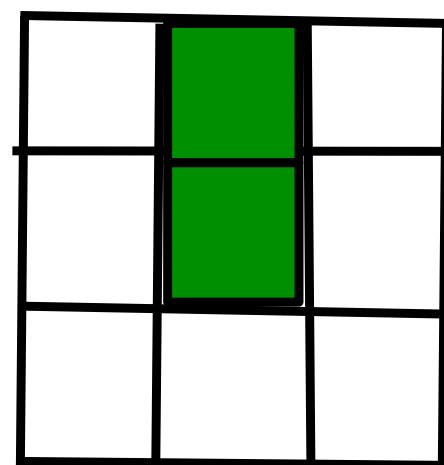
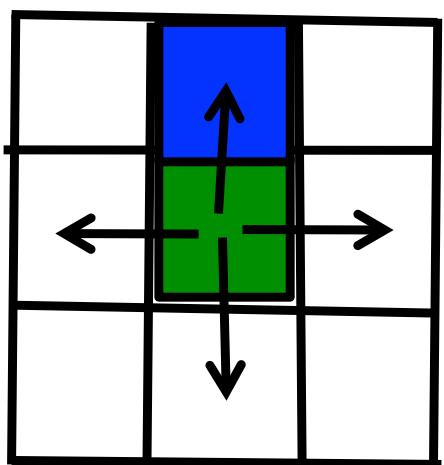
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→ Entities: prey  and predator 

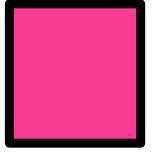
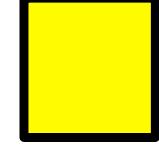
Predator_Prey

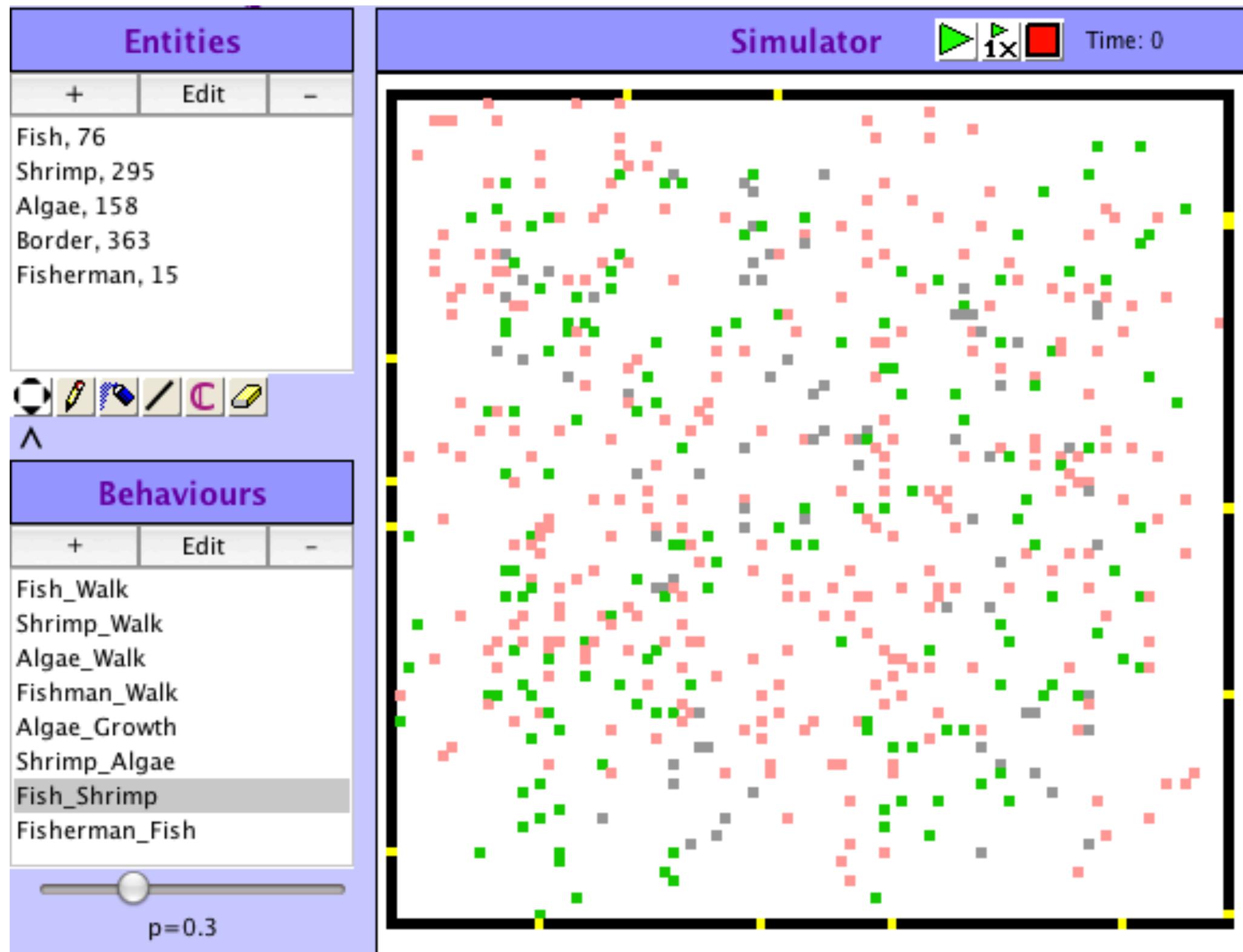


P=0.6



NetBioDyn : 4th example, fish farm

→ Entities: fish  , shrimp  , algae  ,
fisherman  , border 



NetBioDyn : 4th example, fish farm

→ Entities: fish , shrimp , algae ,
 fisherman , border

Entities :

Fish:	$1/2 \text{ Life} = 150.0$
Shrimp:	$1/2 \text{ Life} = 200.0$
Algae:	$1/2 \text{ Life} = \text{infinite}$
Border:	$1/2 \text{ Life} = \text{infinite}$
Fisherman:	$1/2 \text{ Life} = \text{infinite}$

Behaviors :

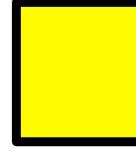
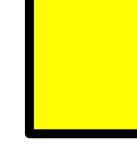
Fish_Walk :	$p=1.0, \text{ Fish} + 0 + *$	$\rightarrow 0 + \text{Fish} + *$
Shrimp_Walk :	$p=1.0, \text{ Shrimp} + 0 + *$	$\rightarrow 0 + \text{Shrimp} + *$
Algae_Walk :	$p=0.3, \text{ Algae} + 0 + *$	$\rightarrow 0 + \text{Algae} + *$
Fishman_Walk :	$p=0.1, \text{ Fisherman} + \text{Border} + *$	$\rightarrow \text{Border} + \text{Fisherman} + *$
Algae_Growth :	$p=0.02, \text{ Algae} + 0 + *$	$\rightarrow \text{Algae} + \text{Algae} + *$
Shrimp_Algae :	$p=0.6, \text{ Shrimp} + \text{Algae} + *$	$\rightarrow \text{Shrimp} + \text{Shrimp} + *$
Fish_Shrimp :	$p=0.3, \text{ Fish} + \text{Shrimp} + *$	$\rightarrow \text{Fish} + \text{Fish} + *$
Fisherman_Fish :	$p=1.0, \text{ Fisherman} + \text{Fish} + *$	$\rightarrow \text{Fisherman} + + *$

Road map

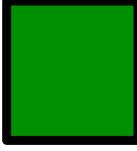
- Multi-Agents Systems (MAS)
- From Biological environment simulation
- Towards Ecosystems simulation
- NetBioDyn software
- Conclusions and futur works

NetBioDyn : Conclusion

- Advantage: → very simple (entities, rules)
→ no programming !

Example:  + Ø → Ø +  (movement)
.....

- Drawback: → very simple (entities, rules)
→ no entity's state !

Example:  + * →  + * (new entity's state)
..... → new entity !

NetBioDyn : futur works

- Self-adjusting parameters...
 → a great challenge !
- Entity's state (simply an integer)...
 → Building a model would be simpler by minimizing the nb of « different » entities